

Improve Power Conversion Efficiency

From DC to 2 MHz, industry's proven solution for high-accuracy power analysis.

The High Accuracy Power Analyzer.



Upgrade New current sensors

Engineered for more accurate power measurement

Improved frequency bandwidth and accuracy



Scan QR Code to Watch Video

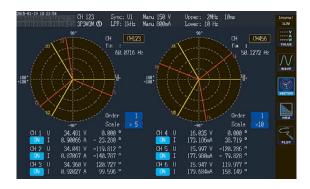


Achieving true power analysis

DC, 0.1 Hz to 2 MHz frequency bandwidth Obtain even greater accuracy in high-frequency power measurements with the aid of Hioki's current sensor phase shift function

A wide frequency range is required for power measurement due to the acceleration of switching devices, especially SiC. High accuracy, broadband, and high stability. The PW6001's world-class technology-based fundamental performance makes in-depth power analysis a reality.





±0.02%* basic accuracy for power Strengthened resistance to noise and temperature fluctuations in the absolute pursuit of measurement stability

The custom-shaped solid shield made completely of finely finished metal and optical isolation devices used to maintain sufficient creepage distance from the input terminals dramatically improve noise resistance, provide optimal stability, and achieve a CMRR performance of 80 dB/100 kHz. Add the superior temperature characteristics of ±0.01%/°C and you now have access to a power analyzer that delivers top-of-the-line measurement stability.

*Device accuracy only

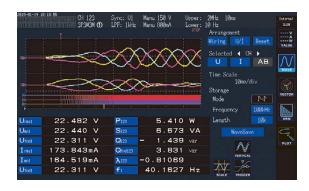


Optical isolation device

18-bit resolution, 5 MS/s sampling

Measurements based on sampling theorem are required to perform an accurate power analysis of PWM waveforms. The Hioki PW6001 features direct sampling of input signals at 5 MS/s, resulting in a measurement band of 2 MHz. This enables analysis without aliasing error.

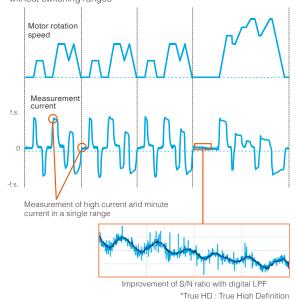




TrueHD 18-bit converter* measures widely fluctuating loads with extreme accuracy

A built-in 18-bit A/D converter provides a broad dynamic range. Even loads with large fluctuations can be shown accurately down to tiny power levels without switching the range. Further, a digital LPF is used to remove unnecessary high-frequency noise, for accurate power analysis.

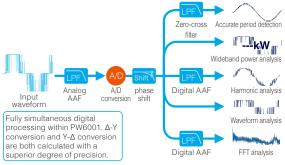
Conversion efficiency measurement during mode measurement without switching ranges



Achieve lightning fast calculations for 5 independent signal paths at the same time with the Power Analysis Engine II



Calculations for up to five independent signal paths (period detection/broadband power analysis/harmonic analysis/waveform analysis/FFT analysis) are independently and digitally processed, eliminating any effects one may have on another. Achieve a 10 ms data update speed while maintaining full accuracy through high-speed processing.



^{*} AAF (Anti-aliasing filter): This filter prevents aliasing errors during sampling.

Functions and Characteristics

Max Speed 10 ms, Maximum 12 ch* High Accuracy Power Calculation

Data updates in 10 ms to 200 ms. Make high speed calculations while maintaining high accuracy. Achieve measurement stability with original digital filter technology, and measure power after automatically tracking frequency fluctuations from 0.1 Hz.



^{*} Two 6-channel model devices, during synchronized function usage

Simple, high-precision efficiency and loss calculations

When measuring DC/AC converter efficiency, accuracy is required not only for AC but also DC. The basic DC measurement accuracy of the PW6001 is $\pm 0.02\%$, enabling you to make accurate and stable efficiency measurements.

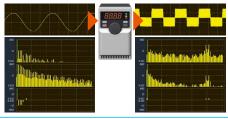


Setting up efficiency calculation formulas for power conditioners and similar equipment is simple on the dedicated screen. Simultaneously display loss and efficiency calculations for a maximum of four systems.

*Device accuracy

Independent harmonic analysis for a maximum of 6 systems (wideband/IEC)

0.1 Hz to 300 kHz fundamental frequency, 1.5 MHz analyzable bandwidth. Comes equipped with IEC61000-4-7-compliant harmonic analysis and up to 100th order wideband harmonic analysis.



Synchronize inverter input/output and each fundamental wave

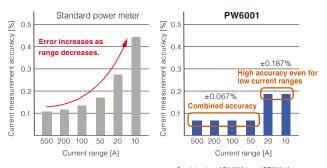
Applications

- Motor fundamental wave analysis
- Wireless power transmission waveforms
- Measuring distortion ratio of power conditioner output waveforms

Achieve high accuracy measurement, including in low current ranges

When used with a high accuracy current sensor*1, the PW6001 delivers exceptional accuracy*2. Achieve high accuracy measurement regardless of range, from high to low currents, even for loads that exhibit significant fluctuation.

Example of combination accuracy with current sensor

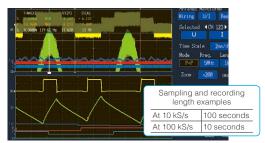


Combination of PW6001 and CT6904A Accuracy achieved when measuring the fullscale current in each range, 45 Hz to 65 Hz.

- *1 Pass-through type: CT6872, CT6873, CT6875A, CT6876A, CT6877A, CT6904A Clamp type: CT6841A, CT6843A, CT6844A, CT6845A, CT6846A Direct connection type: PW9100A
- *2 At DC and 50 Hz/60 Hz

Large-capacity waveform storage for oscilloscope and PQA-level waveform analysis

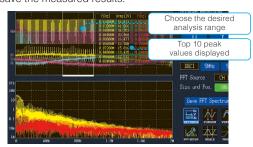
Waveform Storage of 1 MWord × (voltage-current 6 ch + Motor Analysis 4 ch). The torque sensor and encoder signals are displayed along with the voltage and current waveforms.



In addition to the level trigger function, the new event trigger starts recording when there is a fluctuation in RMS values or frequency. Cursor measurement and waveform zoom functions also render oscilloscopes unnecessary for waveform analysis.

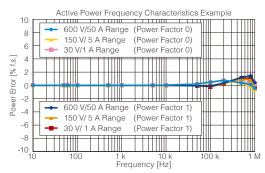
FFT analysis of target waveforms

Analyze frequencies up to 2 MHz across 2 channels. Specify any waveform analysis range you like and view the 10 highest peak values and frequencies. Observe frequency components that do not show up in harmonics and save the measured results.



Flat Frequency Characteristics

Frequency characteristics are flat up to 1 MHz even when the power factor is zero. Use together with the Current Sensor Phase Shift Function (see right) to make highly accurate low power factor measurements of high-frequency waves. It can very useful for assessing loss in high-frequency components like transformers and reactors.

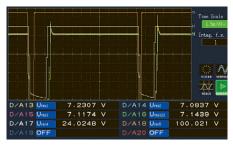


* Options to further improve high-frequency wave phase characteristics available.

Contact us for more information.

D/A Monitor

View up to 8 channels of progressive fluctuations in measured values. Voltage, current, power, frequency and other parameters are updated at the fastest rate of 10 ms, allowing you to observe even the tiniest variations.



Applications

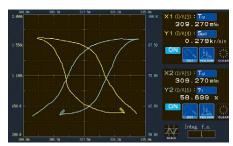
- Power conditioner FRT Analysis
- Motor Transient State Power Analysis

FRT (Fault Ride Through) :

Ability to continue operation despite system disturbance in the power conditioner or similar systems

X-Y Plot

Easily check correlations in measured values for up to two systems simultaneously. Plot physical quantities other than measured values as well by using it together with the user defined calculation function.

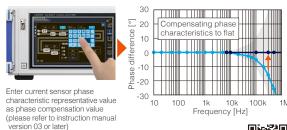


Applications

- Motor characteristics analysis
- Transformer characteristics analysis
- Power conditioner MPPT Analysis

Current Sensor Phase Shift Function

Our original virtual oversampling technology evolved! It allows for phase compensation equivalent to that of a 2 GS/s oscilloscope a reality while maintaining 5 MS/s 18-bit high resolution. With this function, you can perform current sensor phase compensation with a 0.01° resolution, and measure power more accurately. This also makes high frequency, low power factor power measurements more accurate than ever before.



*Scan the QR code on the right to download a technical brief about current sensor phase shift.



Complex calculation formulas settable on the device

Set equations to compute measurement values any way you want. Enter up to 16 calculation formulas, including functions like sin and log. Calculation results can be used as parameters for other calculation formulas, enabling complex analysis.



Applications

- Calculate multisystem efficiency and loss with solar power modules and similar equipment
- Calculate Ld.Lq for motor vector control

Supports various power analysis systems

Improved connectivity to PCs over LAN. Remotely operate the PW6001 using a browser from any PC, tablet, or smartphone via the HTTP server function. Acquire files through the network with the FTP server function. LabVIEW driver and MATLAB Toolkit are also available.



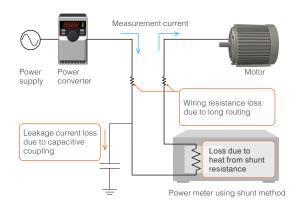
* LabVIEW is a registered trademark of NATIONAL INSTRUMENTS
*MATLAB is a registered trademark of Mathworks, Inc.

Specially designed for current sensors to achieve highly precise measurement

With direct wire connection method

The wiring of the measurement target is routed for connecting to the current input terminal. However, this results in an increase in the effects of wiring resistance and capacitive coupling, and meter loss occurs due to shunt resistance, all of which lead to larger accuracy uncertainty.

Measurement example using the direct wire connection method



Advantages of current sensor method

A current sensor is connected to the wiring on the measurement target. This reduces the effects of wiring and meter loss, allowing measurements with wiring conditions that are close to the actual operating environment for a highly efficient system.

Measurement example using the current sensor method



Compared to the direct wire connection method, measurement with conditions closer to the actual operation environment of a power converter is achieved.

Seamless operability

Simple settings and intuitive operating interface.



9-inch touch screen with soft keypad



Enter handwritten memos on the screen, or use the onscreen keypad



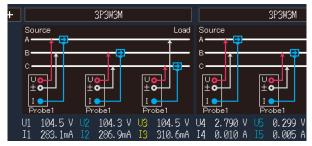




One-touch data saving with dedicated key



Quick Configuration screen*

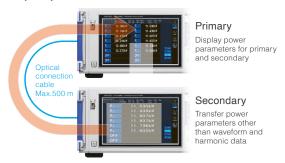


Wiring confirmation function, to avoid wiring mistakes

^{*} A low power factor measurement (LOW PF) mode for easily setting reactor and transformer loss measurement has been added.

Build a 12-channel power meter using "numerical synchronization"

For multi-point measurements, use the numerical synchronization function to transfer power parameters from the secondary device to aggregate at the primary in real-time, essentially enabling you to build a 12-channel power analysis system



- Real-time display of secondary instrument measurement values on primary instrument screen
- Real-time efficiency and loss calculations between primary and secondary instruments
- Save data for 2 units on recording media in primary instrument
- Use the secondary's measured values on the primary's user-defined calculations

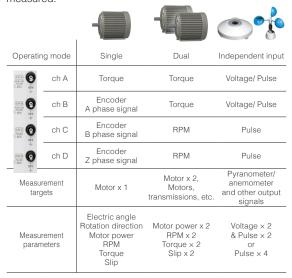
Measure phase difference between 2 separate points

Use the waveform synchronization function to measure the phase relationship between 2 points separated by a maximum distance of 500 m. Due to insulation with an optical connection cable, measurement can be performed safely even if the ground potential between the 2 points is not the same.



Wide range of Motor Analysis functions (Motor Analysis and D/A output model)

Enter signals from torque meters and speed meters to measure motor power. In addition to motor parameters such as motor power and electrical angle, output signals from insolation meters and wind speed meters can also be measured.



Simply transfer waveforms with "waveform synchronization"

Data sampled at 18 bits and 5 MS/s is sent between instruments in real time*, and the waveform measured by the secondary is displayed as-is on the primary instrument. This functionality lets you use the power analyzers to measure the voltage phase difference between two remote locations, for example at power substations, manufacturing plants, or railroad facilities.



Primary

Display max. 6 channels of waveforms for primary and secondary

Secondary

Transfer waveform data for max. 3 channels

- Real-time display of secondary instrument waveforms on primary instrument screen
- Harmonic analysis and fundamental wave analysis for primary instrument and secondary instrument
- Simultaneously measure waveforms on primary device while using the secondary to trigger
- D/A output of the secondary instrument's waveform from the primary instrument
- *For both primary instruments and secondary instrument, waveform synchronization operates only when there are 3 or more channels. Max. ±5 sampling error.

D/A output waveforms captured 500m away

Transfer voltage/current waveforms taken by the secondary instrument located as far as 500m away and output the signals from the primary device. When combined with a Hioki MEMORY HICORDER, timing tests and simultaneous analysis of multiple channels for 3-phase power are possible.



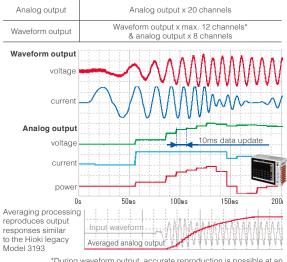
Max. analog 32 channels + logic 32 channels MEMORY HiCORDER MR8827

* The waveform that is output has a delay of 7 μs to 12 μs, depending on the distance.

Analog Output and 1 MS/s Waveform Output

(Motor Analysis and D/A output model)

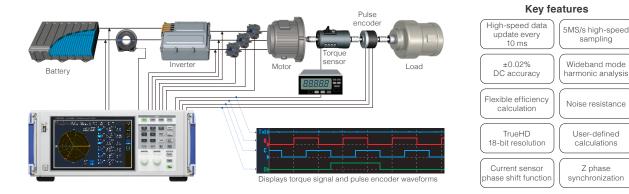
Output analog measurement data at update rates of up to 10ms. Combine with a data logger to record long-term fluctuations, and use the built-in waveform output function to output voltage and current at 1 MS/s*.



*During waveform output, accurate reproduction is possible at an output of 1 MS/s and with a sine wave up to 50 kHz.

Applications

EV/HEV inverter and motor analysis



*Scan the QR code on the right to download a technical brief about SiC inverter power measurements



sampling

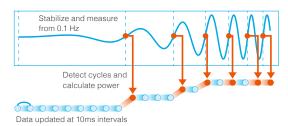
User-defined

calculations

Calculate transient state power with 10 ms high accuracy and high speed

Measure power transient states, including motor operations such as starting and accelerating, at 10 ms update rates. Automatically measure and keep up with power with fluctuating frequencies as low as 0.1 Hz.

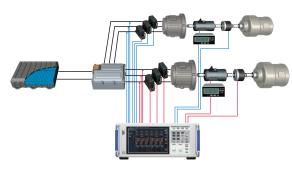
Further more, after a recent update, power calculation is now done every revolution of the motor, making efficiency calculations more stable than ever.



Even during frequency fluctuations from low to high, the fundamental waveform is automatically pursued. Comes equipped with Δ -Y and Y- Δ conversion while calculating with a high degree of accuracy.

Simultaneous measurement of 2 motor powers

The PW6001 is engineered with the industry's first built-in dual mode motor analysis function that delivers the simultaneous analysis of 2 motors. Simultaneous measurement of the motor power for HEV driving and power generation is now possible.



Example of 2 motor measurement

Advanced electrical angle measurement function

Comes equipped with electrical angle measurement necessary for vector control analysis via dq coordination systems as well as high efficiency synchronous motor parameter measurements. Measure voltage and current fundamental wave components based on encoder pulses in real time. In addition, analyze 4 quadrants of torque and rotation through detecting the forward/reverse from A-phasic and B-phasic pulses.



Calculate the Ld and Lq values with user-defined operation

*Scan the QR codes on the right to download technical briefs about electrical angle

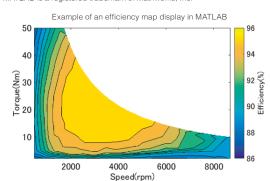




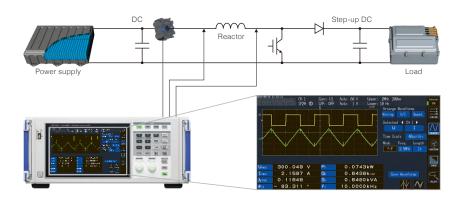
Evaluate inverter motor efficiency and loss

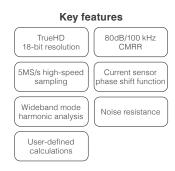
Evaluate efficiency and loss for an inverter, motor, and overall system by simultaneously measuring the inverter's input and output power and the motor's output. You can also create an efficiency map or loss map in MATLAB using measurement results recorded by the PW6001 at each operating point.

*MATLAB is a registered trademark of Mathworks, Inc



Chopper circuit reactor loss measurement





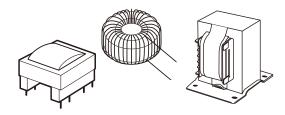
*Scan the QR code on the right to download a technical brief about reactor loss measurements



High-frequency and low power factor device evaluation

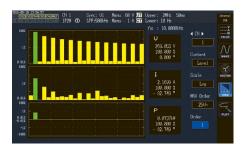
Reactors are used for high harmonic current suppression as well as the voltage step up/down of chopper circuits. The PW6001's outstanding high frequency characteristics, high-speed sampling, and noise-suppressing performance are effective in evaluating high-frequency, low power factor devices (reactors, transformers, etc.).

The low power factor measurement (LOW PF) mode in the simple setting mode makes measurement faster.



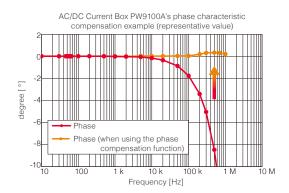
Harmonic analysis synchronized with switching frequencies

With the PW6001 you can perform harmonic analysis of fundamental waves up to 300 kHz with a band frequency of 1.5 MHz. For reactors used by chopper circuits, measure phase angles and RMS values for the current and voltage of each harmonic order through harmonic analysis synchronized with the switching frequency.



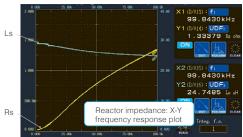
Current Sensor Phase Shift Function

In addition to the PW6001's flat, broad frequency characteristics, sensor phase error compensation allows highly accurate high-frequency and low power factor device analysis.



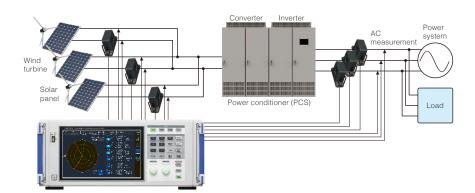
Circuit impedance analysis

Calculate circuit impedance, resistance, and inductance by using harmonic analysis results and user defined calculations. X-Y plot functions are especially effective for impedance analysis.



- Impedance Z $[\Omega]$
- = fundamental frequency voltage / fundamental frequency current \bullet Serial resistance RS $[\Omega]$
- = Z x cos (voltage phase angle current phase angle)
- Serial inductance Ls [H] = $Z \times \sin$ (voltage phase angle current phase angle) / ($Z \times \pi \times \text{frequency}$)

PV/Wind turbine Power Conditioner (PCS) Efficiency Measurement



Key features ±0.02% DC accuracy Various measurement parameters Independent input for Motor Analysis Integration of purchased electricity ±0.01 Hz frequency accuracy Event triggers 2-system vector display

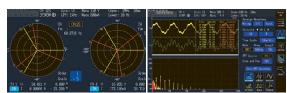
Supports PCS-specific measurements

Simultaneously display the necessary parameters for PCS such as efficiency, loss, fundamental wave reactive power Qfnd, DC ripple ratio, three-phrase unbalanced factor, etc. Easily check the required measured items for improved test efficiency. In addition, by setting the DC power sync source to the output AC power channel, you can perform DC output and stable efficiency measurements perfectly synchronized with the output AC.



Harmonic analysis and conductive noise evaluation

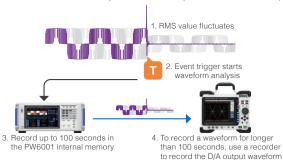
The PW6001 can perform IEC standard-based harmonic measurements that comply with IEC 61000-4-7. In wind power generation, where the generator hardware and grid operate at different frequencies, dual vector displays let you identify the tri-phase equilibrium at a glance. In addition, FFT analysis lets you to evaluate conductive noise generated by devices such as switching power supplies from 2 kHz to 150 kHz.



Measure output harmonics and noise through input waveform FFT analysis

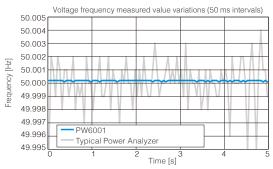
Use event triggers to analyze waveforms

An event trigger function is now available with Ver.3.00. Set triggers for up to four measurement items, such as RMS value and frequency, and record waveforms during an event for up to 100 seconds. If you need to record waveforms for more than 100 seconds, use the D/A output function (Motor Analysis & D/A output option) to observe and record waveforms with a recorder, simplifying the evaluation system. (It is not necessary to connect a differential probe or current probe to the recorder.)



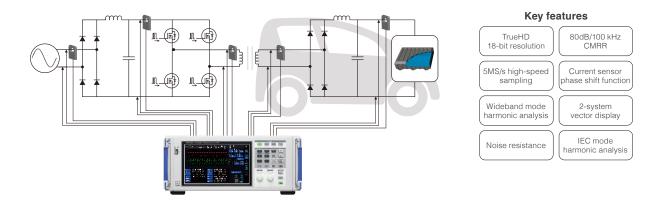
Voltage frequency measurement fundamental accuracy of ± 0.01 Hz*

Perform frequency measurements required for each PCS test with world-class accuracy and stability. Achieve highly accurate frequency measurement values for a maximum of 6 ch (12 ch when there are two devices) while measuring each parameter at the same time.



* ±0.01 Hz fundamental accuracy is defined for cases where the data update is over 50 ms. Please contact us for even more precise frequency measurement.

Measure the efficiency of wireless power transmission (WPT)



Accurate measurement, even of low-power-factor power

In wireless power transfer / transmission (WPT), the inductance component of the energy transmit and receive elements lowers the power factor. The PW6001's current sensor phase shift function can be used to accurately measure high-frequency, low-power-factor power. In WPT measurement, it's extremely effective to combine the PW6001 with a high-bandwidth current measurement tool.



Analyze transmission frequency harmonics

The PW6001's harmonic analysis function can analyze fundamental harmonics of up to 300 kHz at a bandwidth of up to 1.5 MHz. For example, with a circuit that uses an 85 kHz band switching frequency (a frequency that could be used in power transmission in electric vehicle applications) as the fundamental harmonic, the analyzer is capable of simultaneously measuring voltage, current, power, and phase angle for both receive and transmit through the 15th order.



Automatic WPT TEST SYSTEM (For more information, please see the TS2400 product catalog.)

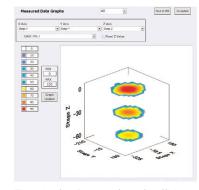
The WPT Evaluation System TS2400 is a system for automatically measuring the reproducible data that is required to evaluate WPT hardware by integrating measurement with an XYZ stage. A single software package provides control and automatic measurement functionality for instrument configuration, transmit and receive device positioning, and data collection. The results of analyses can be presented using a variety of bar graphs.



WPT TEST SYSTEM TS2400

WPT evaluation supports the following types of measurement:

- Power transfer efficiency measurement (using the PW6001)
- Automatic coupling coefficient measurement



Example of a 4D graph of transfer efficiency

Interfaces Names of parts



GP-IB	Data viewable through dedicated application Command control
	Data viewable through dedicated application Command control Bluetooth® logger connection
RS-232C	Send the D/A output of values measured with the PW6001 (maximum of 8 items) wirelessly to the Hioki Wireless Logging Station LR8410 using the dedicated cable and Bluetooth® serial conversion adapter. (Approx. 30m* line of sight)The observable output resolution is dependent on the LR8410's resolution. * The presence of obstructions (walls, metal, etc.) may shorten the communication range or destabilize the signal. * Bluetooth® is a trademark of Bluetooth SIG, Inc. and licensed for use by HIOKI E.E. CORPORATION.
External I/O	START/STOP/DATA RESET control Terminals shared with RS-232C, ±5 V/200 mA power supply possible

View data in free dedicated application

	5	4	3	2				RS-232C, External I/O GP-IB LAN Synchronous control D/A output Motor Analysis Input Current probe input
Synchron	nous	0	otical	conne	ection	cabl	e conne	ector, Duplex-LC (2-core)

Synchronous control	Optical connection cable connector, Duplex-LC (2-core)
D/A output (PW6001-11 to 16 only)	Switching for 20 channels of analog output or maximum 12 channels of waveform + 8 channels of analog output
Current probe input component	Power can also be supplied from the PW6001 to Probe1 or Probe2 by using the sliding cover.

Motor Analysis input component electric angle and motor power from instrument actinometers and anemometers.	als including

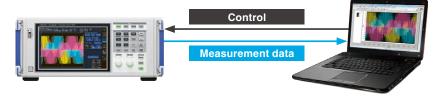
Save interval data (csv) in real time at the fastest interval of 10 ms
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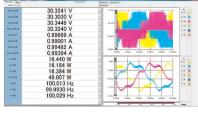
64 MB	Save interval data and
internal memory	send it to a USB flash drive later

Download the communication command manual from the HIOKI website at www.hioki.com

Software

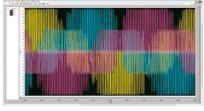
LAN





Gbit LAN supported

Command control





PW Communicator

LabVIEW *

MATLAB *

PC Communication Software - PW Communicator

PC Communicator is a free application that connects to the PW6001 via a communications interface (Ethernet, RS-232C, or GP-IB), making it easy to configure the instrument's settings and to monitor or save measured values and waveform data from a computer. The software can simultaneously connect to up to 8 Hioki power measuring instruments, including the PW6001, Power Analyzer PW3390, Power Meter PW3335, PW3336, and PW3337, and it can provide integrated control over multiple models. The software can also be used to simultaneously save measurement data on the computer and calculate efficiency between instruments.

LabVIEW driver and MATLAB toolkit

Hioki's LabVIEW driver and MATLAB toolkit can be used to build data collection and measurement systems. We also offer a number of sample programs to help you get started.

- *LabVIEW is a registered trademark of National Instruments.
- *MATLAB is a registered trademark of Mathworks, Inc.

Download the software and drivers from the HIOKI website at www.hioki.com

GENNECT One SF4000

The SF4000 is a free application software that lets you display and save measurement data on a PC in real-time after connecting the PW6001 to the PC via Fthernet

The application is also compatible with other Hioki measuring instruments such as Memory HiLogger LR8450 and the Wireless Logging Station LR8410, letting you connect up to 30 units at the same time to monitor, graph and display lists of measured values from multiple instruments all at once and in real-time. This is especially effective for performing a total analysis of power, temperature and other factors of equipment.



Power analyzer lineup

Applications For measurement of high-efficiency IGBT inverters Appearance Measurement frequency band Basic accuracy for 50/60 Hz power Accuracy for DC power Accuracy for 10 kHz power Accuracy for 50 kHz	balance of high accuracy and portability DC, 0.5 Hz to 200 kHz ±(0.04% of reading	
Measurement frequency band DC, 0.1 Hz to 2 MHz DC, 0.1 Hz to 5 MHz E(0.02% of reading + 0.05% of range) ±(0.05% of range) + 0.05% of reading + 0.05% of reading + 0.05% of range) ±(0.02% of reading + 0.05% of range) ±(0.2% of reading + 0.05% of range) ±(0.4% of reading + 0.05% of range) ±(0.4% of reading + 0.05% of range) ±(0.15% of reading + 0.05% of range) ±(0.4% of reading + 0.05% of r	0 1 MHz DC, 0.5 Hz to 200 kHz ting ±(0.04% of reading	
Basic accuracy for 50/60 Hz power	ting ±(0.04% of reading	
Accuracy for 50/60 Hz power		
Accuracy for DC power + 0.05% of range) + 0.03% of range) + 0.05% of range) + 0.05% of range) + 0.05% of range) + 0.05% of reading + 0.05% of reading + 0.05% of range) + 0.05% of range) + 0.05% of range) + 0.05% of range) Accuracy for 50 kHz power ±(0.15% of reading + 0.1% of range) ±(0.15% of reading + 0.05% of range) + 0.05% of range) + 0.1% of range) Number of power measurement 1 to 6 channels, a specify when 1 to 8 channels, specify U7001 or		
Accuracy for 10 kHz power + 0.1% of range) + 0.05% of reading + 0.1% of range) + 0.05% of range) + 0.1% of range) + 0.05% of range) + 0.1% of range) + 0.1% of range) + 0.05% of range) + 0.1% of range) + 0.1% of range) + 0.05% of		
Accuracy for 50 kHz power ±(0.15% of reading + 0.1% of range) ±(0.4% of reading + 0.05% of range) ± (0.4% of reading + 0.1% of range) + 0.1% of range) + 0.1% of range) ± (0.4% of reading + 0.1% of range) + 0.1% of reading + 0.1% of re		
Number of power measurement 1 to 6 channels, a specify when 1 to 8 channels, specify U7001 or	±(0.4% of reading	
Voltage, current ADC sampling 18-bit, 5 MHz 18-bit, 15 MHz 18-bit, 15 MHz	4 shannala	
E Voltage, current ADO sampling 10 bit, 5 Wil iz 10 bit, 15 Wil iz 10 bit, 2.5	,	
6 V/15 V/30 V/60 V/150 V/	15 V/30 V/60 V/150 V/	
Voltage range 300 V/600 V/150 V 6 V/15 V/30 V/60 V/150 V/ 300 V/600 V/150 V	300 V/600 V/1500V	
Channels Ordering U7005 when placing an order (mixed available place)	ed on sensor) 100 mA to 8000 A	
Common-mode voltage rejection ratio 50/60 Hz: 100 dB or greater 100 kHz: 80 dB typical 50/60 Hz: 120 dB or greater 100 kHz: 110 dB or greater 100 kHz: 110 dB or greater 100 kHz: 80 dB		
Temperature coefficient 0.01%/°C 0.01%/°C	0.01%/°C	
Voltage input method Photoisolated input, Photoisolated input, resistor voltage division Photoisolated input, resistor voltage division resistor voltage		
Current input method Isolated input from current sensor Isolated input from current sensor	Isolated input from current sensor	
External current sensor input Yes (ME15W, BNC) Yes (ME15W) Yes (ME15W	V, BNC) Yes (ME15W)	
Power supplied to external current sensor Yes Yes	Yes	
Data update rate 10 ms, 50 ms, 200 ms 1 ms, 10 ms, 50 ms, 200 ms	50 ms	
Maximum input voltage 1000 V,±2000 V peak (10 ms) 1000 V,±2000 V peak 1000 V AC, 15 ±2000 V peak Maximum rated 600 V CAT III 600 V CAT III 600 V AC/1000 V		
Maximum rated 600 V CAT III 600 V CAT III 600 V CAT III 600 V CAT III 1000 V CAT		
Number of motor analysis channels Maximum 2 motors*1 Maximum 4 motors*1 Motor analysis input format Analog DC, frequency, pulse Analog DC, frequency, pulse	Maximum 1 motors*1	
Motor analysis input format Analog DC, frequency, pulse Analog DC, frequency, pulse	Analog DC, frequency, pulse	
Current sensor phase shift calculation Yes Yes (auto)	Yes	
Harmonics measurement Yes (6, for each channel) Yes (8, for each channel)	Yes	
Maximum harmonics analysis order 100th 500th	100th	
Harmonics synchronization frequency range 0.1 Hz to 300 kHz 0.1 Hz to 1.5 MHz 0.1 Hz to 1	1 MHz 0.5 Hz to 5 kHz	
IEC flicker measurement Yes Yes*2 IEC flicker measurement Yes Yes*2	-	
FFT spectrum analysis Yes (DC to 2 MHz) Yes*2 (DC ~ 4 MHz) Yes*2 (DC ~ 6 MHz)	1 MHz) Yes (DC to 200 kHz)	
User-defined calculations Yes Yes	res (DC to 200 KHz)	
Delta conversion $Yes (\Delta-Y, Y-\Delta)$ $Yes (\Delta-Y, Y-\Delta)$	Yes (Δ-Y)	
D/A output Yes*1 20 ch (waveform output, analog output) Yes*1 20 ch (waveform output, analog output)	Ves*1 16 ch	
	9" WVGA TFT color LCD	
Display 9" WVGA TFT color LCD 10.1" WVGA TFT color LCD Touch screen Yes	-	
External storage media USB 2.0 USB 3.0	USB 2.0, CF card	
LAN (100BASE-TX, 1000BASE-T) Yes Yes	Yes (10BASE-T and 100BASE-TX only)	
GP-IB Yes Yes	-	
RS-232C Yes (maximum 230,400 bps) Yes (maximum 115,200 bps) External control Yes Yes	Yes (maximum 38,400 bps)	
External control Yes Yes	Yes	
Synchronization of multiple instruments - Yes*2 (up to 4 instruments)	Yes (up to 8 instruments)	
Optical link Yes Yes***2	-	
CAN or CAN FD - Yes*1	-	
Dimensions, weight (WxHxD) 430 mm (16.93 in.) × 177 mm (6.97 in.) × 450 mm (17.72 in.) 14 kg (493.84 oz.) 430 mm (16.93 in.) × 221 mm (8.70 in.) × 361 mm (14.21 in.) 14 kg (493.84 oz.) 340 mm (16.93 in.) × 221 mm (8.70 in.) × 361 mm (14.21 in.) 14 kg (493.84 oz.)		

^{*1:} Sold separately *2: This is a feature that will be supported in the upcoming firmware update to Ver. 2.0.

Specifications

Power measurement

Measurement lines									
			V), 1-phase/3-wir V2M, 3V3A, 3P3		o/4-wiro (3P4V	V)			
	CH1	CH2	CH3	CH4	CH5	CH6			
Pattern 1	1P2W	1P2W	1P2W	1P2W	1P2W	1P2W			
Pattern 2	1P3W / 3		1P2W	1P2W	1P2W	1P2W			
Pattern 3	1P3W / 3		1P2W	1P3W /	3P3W2M	1P2W			
Pattern 4	1P3W / 3			BP3W2M	1	3P3W2M			
					-	т			
Pattern 5		V3M / 3V3A		1P2W	1P2W	1P2W			
Pattern 6		V3M / 3V3A		-	3P3W2M	1P2W			
Pattern 7	_	V3M / 3V3A	/ 3P4W nations, select 1F		W3M / 3V3A / 3	3P4W			
			nations, select 11 nations, select 3f						
Number of	1	2	3	4	5	6			
channels			-	·					
Pattern 1	/	/	/	/	/	/			
Pattern 2	-	✓	/	/	/	/			
Pattern 3	-	-	-	-	-	/			
Pattern 4	-	-	-	/	-	/			
Pattern 5	-	-	/	/	/	/			
Pattern 6	-		-	-	/	/			
Pattern 7	-		-	_	_	/			
			that can be selec		the number of	channels:			
	[v] Can b	e selectea,	[-] Cannot be sel	ected					
lumber of input	Max 6 c	hannels: ea	ch input unit pro	vides 1 chani	nel for simultar	neous voltage			
hannels	and curre		on input unit pro	*1000 1 011a111	ioi ioi oiiiiaitai	noodo vonagi			
	Voltage	Plua-in	terminals (safet	v terminals)					
nput terminal profile	Probe 1	Dedica	ited connector (N	ME15W)					
	Probe 2		netal) + power si						
Proho 2 novembrani	+12 V ±0	.5 V, -12 V :	±0.5 V, max. 60	0 mA, up to a	max. of 700 r	mA for up to 3			
Probe 2 power supply	channels			, , ,					
	Voltage	measuremer	nt unit Photoiso	lated input, re	sistance voltaç	ge divider			
nput method		neasuremer			rent sensor (vo				
/oltage range	6 V / 15 V	/30 V /60 V	V / 150 V / 300 V	/ 600 V / 1500	V				
	_					`			
			A / 4 A / 8 A / 20 A / 80 A / 200 A	A	(with 20 A sen (with 200 A se				
Current range			0 A/ 800 A/ 2 kA		(with 2000 A se	,			
Probe 1)		/5 A / 10 A			(with 50 A sen				
			00 A / 200 A / 500) A	(with 500 A se				
	20 A / 40	A / 100 A / 2	200 A / 400 A / 1	kA	(with 1000 A s	ensor)			
) kA / 20 kA / 50 l						
			/1 kA/2 kA/5						
Probe 2)	10 A / 20	10 A / 20 A / 50 A / 100 A / 200 A / 500 A (with 10 mV/A sensor; with 3274 or 3275)							
	1 A / 2 A	1 A / 2 A / 5 A / 10 A / 20 A / 50 A (with 100 mV/A sensor; with 3273 or 3276)							
	100 mA /	100 mA / 200 mA / 500 mA / 1 A / 2 A / 5 A (with 1 V/A sensor; with CT6700 or CT6701)							
	(0.1 V / 0.	2 V / 0.5 V /	1.0 V / 2.0 V / 5.0	V range)					
Power range	2.40000	N to 9.0000	0 MW (depending	g on voltage a	nd current com	nbinations)			
	3 (relative	to voltage/	current range rat	ing);					
Crest factor	however,	3 (relative to voltage/current range rating); however, 1.33 for 1500 V range, 1.5 for 5 V Probe 2 range 300 (relative to minimum valid voltage and current input);							
			ium valid voltage 0 V range, 150 fo						
					ungo				
	Voltage i		4 MΩ ±40 kΩ	Probe 2 in	oute 1 M	0 +50 k0			
input resistance (50 Hz / 60 Hz)	Probe 1		4 MΩ ±40 kΩ 1 MΩ ±50 kΩ	Probe 2 in	puts 1 M	Ω ±50 kΩ			
		inputs	1 MΩ ±50 kΩ 1000 V, ±2000 V	/peak (10 ms o	or less)				
	Probe 1	inputs	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequency	/peak (10 ms o	or less) Iz to 1 MHz, (125	50 - f) V			
50 Hz / 60 Hz)	Probe 1 Voltage i	inputs	1 MΩ ±50 kΩ 1000 V, ±2000 V	/peak (10 ms of uency of 250 kH quency of 1 M	or less) Iz to 1 MHz, (125	50 - f) V			
50 Hz / 60 Hz)	Probe 1 Voltage i Probe 1	inputs nputs	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequent voltage frequent voltage frequent for f above: 5 V, ±12 Vpeak (/peak (10 ms of uency of 250 kH quency of 1 M kHz 10 ms or less)	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V			
50 Hz / 60 Hz)	Probe 1 Voltage i	inputs nputs	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequent vol	/peak (10 ms of uency of 250 kH quency of 1 M kHz 10 ms or less)	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V			
50 Hz / 60 Hz) Maximum input voltag	Probe 1 Voltage i Probe 1 Probe 2	inputs inputs inputs inputs	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequent voltage frequent voltage frequent for f above: 5 V, ±12 Vpeak (/peak (10 ms of uency of 250 kH quency of 1 M kHz 10 ms or less)	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V			
50 Hz / 60 Hz) Maximum input voltag	Probe 1 Voltage i Probe 1 Probe 2 Voltage ii CATIII 60	inputs inputs inputs inputs input termina 0V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (I (50 Hz/60 Hz) led transient ove	/peak (10 ms of Jency of 250 kH quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V			
50 Hz / 60 Hz) Maximum input voltag Maximum rated voltag	Probe 1 Voltage i Probe 1 Probe 2 Voltage ii CATIII 60	inputs inputs inputs inputs input termina 0V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (I (50 Hz/60 Hz)	/peak (10 ms of Jency of 250 kH quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V			
fo Hz / 60 Hz) Aaximum input voltage Aaximum rated voltage o earth	Probe 1 Probe 1 Probe 2 Voltage ii Probe 2 Voltage ii CATIII 60 CATII 100 Voltage/o	inputs inputs inputs inputs input termina 0V; anticipal 10V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (I (50 Hz/60 Hz) led transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
fo Hz / 60 Hz) Aaximum input voltage Aaximum rated voltage o earth	Probe 1 Voltage i Probe 1 Probe 2 Voltage ii CATIII 60 CATII 100 Voltage/c calculatio	inputs inputs inputs input termina 0V; anticipal 0V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
50 Hz / 60 Hz) Maximum input voltage Maximum rated voltage o earth Measurement method	Probe 1 Probe 1 Probe 2 Voltage ii Probe 2 Voltage ii CATIII 60 CATII 100 Voltage/o	inputs inputs inputs input termina 0V; anticipal 0V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
Aaximum input voltag Maximum rated voltage o earth Measurement method Sampling	Probe 1 Voltage i Probe 2 Voltage ii CATIII 60 CATII 100 Voltage/calculatio	inputs inputs inputs input termina 0V; anticipal 0V; anticipal	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
Aaximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band	Probe 1 Probe 2 Probe 2 Voltage is CATIII 60 CATIII 00 Voltage/calculatic	inputs inputs inputs inputs input termina in	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization	Probe 1 Voltage i Probe 2 Voltage ii CATIII 60 CATII 100 Voltage/calculatio	inputs inputs inputs inputs input termina in	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of uency of 250 kH- quency of 1 M kHz 10 ms or less) 10 ms or less) rvoltage: 6000 ervoltage: 6000	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
	Probe 1 Voltage i Probe 2 Probe 2 CATIII 60 CATIII 100 Voltage/calculatio 5 MHz / 1 DC, 0.1 Hz to	inputs inputs inputs inputs input termina 00'; anticipa 100'; anticipa current simu in 8 bits z to 2 MHz	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freq Input voltage fre Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove	/peak (10 ms of the control of the control of 250 kH quency of 1 N kHz 10 ms or less) 10 ms or less) 10 ms or less) rvoltage: 6000 prvoltage: 6000 sampling wi	or less) lz to 1 MHz, (125 Hz to 5 MHz, 5	50 - f) V 50 V			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATIII 60 CATIII 50 CATII	inputs inputs inputs inputs inputs input termina 0V; anticipation current simu at 2 MHz 11 to 16, DC xt2, Zph, C-	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequent voltage frequen	(peak (10 ms or unercy of 250 kH quercy of 250 kH quercy of 11 kHz kHz (10 ms or less) 10 ms or less) which gets (10 kHz (10 kHz) and gets (10 kHz) an	or less) or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 DV DV th zero-cross	i0 - f) V i0 V synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization	Probe 1 Voltage is Probe 2 Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculation 5 MHz / 1 DC, 0.1 Hz to U1 to U6, Ext to E The zero	inputs inputs inputs inputs inputs input termina input ter	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequent input voltage frequent input voltage frequent input voltage frequent infor f above: 5 V, ±12 Vpeak (150 Hz/60 Hz) ted transient over the detail interest into the input voltage in the inp	(peak (10 ms of centry of 250 kH quency of 250 kH quency of 150 kHz at 10 ms or less) 11 ms or less) 12 ms or less) 12 ms or less) 13 ms or less) 13 ms or less) 14 ms or less) 15 ms or less) 15 ms or less) 16 ms or less) 16 ms or less) 17 ms or less) 17 ms or less) 18 ms or l	or less) or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 DV DV th zero-cross	i0 - f) V i0 V synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a	inputs inputs inputs inputs input termina ov; anticipa ov; anticipa input termina in 8 bits z to 2 MHz 11 to 16, DC xt2, Zph, CF- cross point s the standa	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequence input voltage input volt	(peak (10 ms of centry of 250 kH quency of 250 kH quency of 150 kHz at 10 ms or less) 11 ms or less) 12 ms or less) 12 ms or less) 13 ms or less) 13 ms or less) 14 ms or less) 15 ms or less) 15 ms or less) 16 ms or less) 16 ms or less) 17 ms or less) 17 ms or less) 18 ms or l	or less) or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 DV DV th zero-cross	i0 - f) V i0 V synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATIII 60 CATIII 60 Calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5	inputs inputs inputs inputs inputs input termina oV; anticipation ov; anticipation at 2 MHz If to I6, DC xt2, Zph, CH- cross point s the standa 0 ms / 200 m	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequency Input voltage frequency Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted transient ove ted transient ove (fixed at data up IC, CH D of the waveform of for U or I select is	(peak (10 ms or usercy of 250 kH query of 250 kH query of 150 kH query of 150 kHz (10 ms or less) 10 ms or less) which is a sampling will date rate), after passing tition.	or less) or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 OV OV th zero-cross	synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used as 10 ms / 5 When us	inputs inputs inputs inputs inputs input termina oV; anticipation ov; anticipation at 2 MHz If to I6, DC xt2, Zph, CH- cross point s the standa 0 ms / 200 m	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage free Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (I (50 Hz/60 Hz) Led transient ove ted	(peak (10 ms or usercy of 250 kH query of 250 kH query of 150 kH query of 150 kHz (10 ms or less) 10 ms or less) which is a sampling will date rate), after passing tition.	or less) or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 OV OV th zero-cross	synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5 When us of average	inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa input termina 8 bits z to 2 MHz If to I6, DC xtz, Zph, Ct cross point is the standa 0 ms / 200 m ng simple a ing simple a ing gimple a ing iteration	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequence input voltage input volt	(peak (10 ms or lensy of 250 kH quency of 250 kH quency of 150 kHz quency of 1 ms or less) 10 ms or less) 10 ms or less) 10 ms or less) 10 ms or less) exportage: 6000 rvoltage: 6000 is sampling will attend the peak graph of the	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 IV DV DV th zero-cross through the zero-varies based of	synchronized			
Maximum input voltage Maximum rated voltage Dearth Measurement method Sampling Frequency band Synchronization Frequency range Synchronization source Data update rate	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E When us of averag 500 Hz / Approx. 5	inputs inputs inputs inputs input termina ov; anticipal ov	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequence Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) led transient ove ted transient ov	(peak (10 ms c lency of 250 kH quency of 250 kH quency of 150 kHz Hz lency of 250 kHz lency of 150 kHz lency	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 IV DV DV th zero-cross through the zero-varies based of	synchronized			
Maximum input voltage Maximum rated voltage Dearth Measurement method Sampling Frequency band Synchronization Frequency range Synchronization source Data update rate	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculation 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Beat 1 to E SWhen us of average 500 Hz / Approx. 5 Except w	inputs inputs inputs inputs inputs input termina ov; anticipat ov; anticipat ov; anticipat ov; anticipat in 8 bits z to 2 MHz If to I6, DC xt2, Zph, Cf- cross point is the standa 0 ms / 200 m g simple a ing iteration I kHz / 5 kH; ov Alta analo hen off, add	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage free Unit for f above: 5 V, ±12 Vpeak (1 (50 Hz/60 Hz) ted transient ove	(peak (10 ms or jene) (peak (10 ms or jene) of 250 kH query of 250 kH query of 150 kHz (10 ms or jess) 10 ms or	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § OV Oth zero-cross through the zero-cross varies based of	synchronized			
Aaximum input voltage Aaximum rated voltage be earth Aeasurement method Sampling requency band Synchronization requency range Synchronization source Data update rate	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculation 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Beat 1 to E SWhen us of average 500 Hz / Approx. 5 Except w	inputs inputs inputs inputs inputs input termina ov; anticipat ov; anticipat ov; anticipat ov; anticipat in 8 bits z to 2 MHz If to I6, DC xt2, Zph, Cf- cross point is the standa 0 ms / 200 m g simple a ing iteration I kHz / 5 kH; ov Alta analo hen off, add	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequence Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) led transient ove ted transient ov	(peak (10 ms or jene) (peak (10 ms or jene) of 250 kH query of 250 kH query of 150 kHz (10 ms or jess) 10 ms or	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § OV Oth zero-cross through the zero-cross varies based of	synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range Synchronization sourc Data update rate	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5 When us of averag 500 Hz / Approx. 5 Except w Defined f	inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa input termina in	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage free Unit for f above: 5 V, ±12 Vpeak (1 (50 Hz/60 Hz) ted transient ove	(peak (10 ms or lensy of 250 kH quency of 250 kH quency of 150 kHz long of 10 ms or less) which is ampling will also be supported by the sampling will also less of the sampling will be sam	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § OV Oth zero-cross through the zero-cross varies based of	synchronized			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range Synchronization sourc Data update rate	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E When us of averag 500 Hz / Approx. 5 Except w Defined fi Current z	inputs inputs inputs inputs input termina ov; anticipal ov	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequency Input voltage frequency Unit for f above: 5 V, ±12 Vyeak (15 V + 12 Vyeak (16 V + 12 Vyeak (17 V + 12 Vyeak (18 V +	(peak (10 ms c lency of 250 kH quency of 250 kH quency of 150 kHz lency of 250 kHz lency of 150 kHz lency of	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 IV DV DV th zero-cross through the zero-waries based of 500 kHz / OFF orth characteris	synchronizes			
Maximum input voltage Maximum rated voltage o earth Measurement method Sampling Frequency band Synchronization requency range Synchronization source Data update rate PF Polarity detection roltage	Probe 1 Voltage is 9 Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Extra to E When us of average 500 Hz / Approx. 5 Except w Defined f Current z	inputs inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa ov; anticipa input termina 8 bits z to 2 MHz If to I6, DC xt2, Zph, Cf- cross point is the standa o ms / 200 m g simple a ing iteration If kHz / 5 kH: O0 kHz analo hen off, add or frequencie	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage free Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove ted	(peak (10 ms or jene) (peak (10 ms or jene) of 1250 kH query of 1250 kH query of 1250 kH query of 14 ms or jene) 10 ms or jene) 11 ms or jene) 11 ms or jene) 11 ms or jene) 11 ms or jene) 12 ms or jene) 13 ms or jene) 13 ms or jene) 14 ms or jene) 15 ms or jene	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § NO O O O O O O O O O O O O O O O O O	synchronized ero-cross filter on the number tics equivalent trequency.			
Aaximum input voltage Aaximum rated voltage o earth Aeasurement method Sampling Frequency band Synchronization requency range Synchronization sourc Data update rate PF	Probe 1 Voltage is 9 Probe 1 Probe 2 Voltage is CATIII 60 CATI	inputs inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa surrent simu in 8 bits z to 2 MHz If to 16, DC xt2, Zph, Ch- cross point is the standa 0 ms / 200 m ng simpation 1 kHz / 5 kH: 00 kHz analo hen off, add or frequenci ero-cross tir U), current er factor (X),	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequency Input voltage frequency Unit for f above: 5 V, ±12 Vyeak (15 V + 12 Vyeak (16 V + 12 Vyeak (17 V + 12 Vyeak (18 V +	(peak (10 ms cuency of 250 kH quency of 250 kH quency of 150 kHz / 10 ms or less) 4 ms or less) 4 ms or less) 4 ms or less) 10 ms or less) 10 ms or less) 10 ms or less) 10 ms or less) 11 ms or less) 11 ms or less) 12 ms or less) 12 ms or less) 12 ms or less) 13 ms or less) 13 ms or less) 14 ms or less) 15 ms or less) 15 ms or less) 16 ms or less) 16 ms or less) 17 ms or less) 17 ms or less) 18	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 5 IV DV DV th zero-cross through the zero varies based of 500 kHz / OFF orth characteris to 1/10 of the series tt power (S), rr,), efficiency (n	synchronized erro-cross filter on the number tics equivalent tfrequency.			
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Aaximum input voltage Aaximum rated voltage	Probe 1 Voltage is Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5 When us of average 500 Hz / Approx. 5 Except w Defined fr Current z Voltage (O), power into	inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa ov; anticipa input termina in	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage frequence input voltage	(peak (10 ms c lency of 250 kH quency of 250 kH quency of 150 kHz (http://doi.org/10.100 kHz /10 ms or less) 10 ms or less) 11 ms or less) 11 ms or less) 12 ms or less) 12 ms or less) 12 ms or less) 13 ms or less) 14 ms or less) 15 ms or less) 15 ms or less) 16 ms or less) 16 ms or less) 16 ms or less) 17 ms or less) 17 ms or less) 18	or less) Iz to 1 MHz, (125 Hz to 5 MHz, 5 Hz to 5 MHz, 6 Hz to 5 MHz, 7 Hz to 5 M	synchronized erro-cross filter on the number tics equivalent tfrequency.			
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Aaximum input voltage Aaximum rated voltage Dearth Aeasurement method Sampling Frequency band Synchronization Requency range Data update rate Dearth Polarity detection Oltage Aeasurement	Probe 1 Voltage is 9 Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5 When us of average Soo Hz / Approx. 5 Except w Defined f Current z Voltage ((Q), powwoltage r power int Voltage, Select frc.	inputs inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa ov; anticipa input termina 8 bits z to 2 MHz If to I6, DC xt2, Zph, CF- cross point is the standa 0 ms / 200 m g simple a ing iteration If kHz / 5 kHz ov kHz ov kHz ov kHz input inp	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage free Input voltage free Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove te	(peak (10 ms or peak	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § NV OV th zero-cross through the zero varies based of 500 kHz / OFF orth characteris to 1/10 of the ser it power (S), rr,), efficiency (n, rf), current in peak (lpk)	synchronized ero-cross filter on the number tics equivalent tit frequency.			
faximum input voltage faximum rated voltage earth feasurement method sampling requency band synchronization requency range synchronization source that a update rate PF folarity detection oltage feasurement arameters effective measuremen ange	Probe 1 Voltage is 9 Probe 1 Probe 2 Voltage is CATII 100 CATII 100 Voltage/calculatic 5 MHz / 1 DC, 0.1 H 0.1 Hz to U1 to U6, Ext1 to E The zero is used a 10 ms / 5 When us of average Soo Hz / Approx. 5 Except w Defined f Current z Voltage ((Q), powwoltage r power int Voltage, Select frc.	inputs inputs inputs inputs inputs input termina ov; anticipa ov; anticipa ov; anticipa ov; anticipa input termina 8 bits z to 2 MHz If to I6, DC xt2, Zph, CF- cross point is the standa 0 ms / 200 m g simple a ing iteration If kHz / 5 kHz ov kHz ov kHz ov kHz input inp	1 MΩ ±50 kΩ 1000 V, ±2000 V Input voltage freu Input voltage freu Unit for f above: 5 V, ±12 Vpeak (8 V, ±15 Vpeak (1 (50 Hz/60 Hz) ted transient ove te	(peak (10 ms or peak	or less) Iz to 1 MHz, (125 Hz to 5 MHz, § NV OV th zero-cross through the zero varies based of 500 kHz / OFF orth characteris to 1/10 of the ser it power (S), rr,), efficiency (n, rf), current in peak (lpk)	synchronized ero-cross filter on the number tics equivalent tit frequency.			

Sine wave input with a power factor of 1 or DC input, terminal-to-ground voltage of 0 V, after zero-adjustment Within the effective measurement range

	Voltage (U)	Current (I)
DC	±0.02% rdg. ±0.03% f.s.	±0.02% rdg. ±0.03% f.s.
0.1 Hz ≤ f < 30 Hz	±0.1% rdg. ±0.2% f.s.	±0.1% rdg. ±0.2% f.s.
30 Hz ≤ f < 45 Hz	±0.03% rdg. ±0.05% f.s.	±0.03% rdg. ±0.05% f.s.
45 Hz ≤ f ≤ 66 Hz	±0.02% rdg. ±0.02% f.s.	±0.02% rdg. ±0.02% f.s.
66 Hz < f ≤ 1 kHz	±0.03% rdg. ±0.04% f.s.	±0.03% rdg. ±0.04% f.s.
1 kHz < f ≤ 50 kHz	±0.1% rdg. ±0.05% f.s.	±0.1% rdg. ±0.05% f.s.
50 kHz < f ≤ 100 kHz	±0.01×f% rdg. ±0.2% f.s.	±0.01×f% rdg. ±0.2% f.s.
100 kHz < f ≤ 500 kHz	±0.008×f% rdg. ±0.5% f.s.	±0.008×f% rdg. ±0.5% f.s.
500 kHz < f ≤ 1 MHz	±(0.021×f-7)% rdg. ±1% f.s.	±(0.021×f-7)% rdg. ±1% f.s.
Frequency band	2 MHz (-3 dB, typical)	2 MHz (-3 dB, typical)

	Active power (P)	Phase difference
DC	±0.02% rdg. ±0.05% f.s.	_
0.1 Hz ≤ f < 30 Hz	±0.1% rdg. ±0.2% f.s.	±0.1°
30 Hz ≤ f < 45 Hz	±0.03% rdg. ±0.05% f.s.	±0.05°
45 Hz ≤ f ≤ 66 Hz	±0.02% rdg. ±0.03% f.s.	±0.05°
66 Hz < f ≤ 1 kHz	±0.04% rdg. ±0.05% f.s.	±0.05°
1 kHz < f ≤ 10 kHz	±0.15% rdg. ±0.1% f.s.	±0.4°
10 kHz < f ≤ 50 kHz	±0.15% rdg. ±0.1% f.s.	±(0.040×f)°
50 kHz < f ≤ 100 kHz	±0.012×f% rdg. ±0.2% f.s.	±(0.050×f)°
100 kHz < f ≤ 500 kHz	±0.009×f% rdg. ±0.5% f.s.	±(0.055×f)°
500 kHz < f ≤ 1 MHz	±(0.047×f-19)% rdg. ±2% f.s.	±(0.055×f)°

- Unit for f in accuracy calculations as mentioned in the table above: kHz
 Voltage and current DC values are defined for Udc and Idc, while frequencies other
 than DC are defined for Urms and Irms.
- When U or I is selected as the synchronization source, accuracy is defined for
- When U or I is selected as the synchronization source, accuracy is defined for source input of at least 5% f.s.
 The phase difference is defined for a power factor of zero during f.s. input.
 Add the current sensor accuracy to the above accuracy figures for current, active power, and phase difference.
 For the 6 V range, add ±0.05% f.s. for voltage and active power.
 Add ±20 μV to the DC accuracy for current and active power when using Probe 1 (however, 2 V f.s.).
 Add ±0.05% rdg. ±0.2% f.s. for current and active power when using Probe 2, and add ±0.05% rdg. ±0.2% f.s. for current and active power when using Probe 2, and add ±0.05% rdg. ±0.2% f.s. for current and active power when using Probe 2, and add ±0.05% rdg. ±0.2% f.s. for current and active power when using Probe 2, and add ±0.05% rdg. ±0.2% f.s. for current and active power when using Probe 2.

- add ±0.2° to the phase at or above 10 kHz.

 The accuracy figures for voltage, current, active power, and phase difference for 0.1
- His decentary figures for voltage, active power, and phase difference in excess of 220 V from 10 Hz to 16 Hz are reference values.

- 220 V from 10 Hz to 16 Hz are reference values.
 The accuracy figures for voltage, active power, and phase difference in excess of 750 V for values of f such that 30 kHz < f ≤ 100 kHz are reference values.
 The accuracy figures for voltage, active power, and phase difference in excess of (22000/I [kHz]) V for values of f such that 100 kHz < f ≤ 1 MHz are reference values.
 Add ±0.02% rdg. for voltage and active power at or above 1000 V (however, figures are reference values).
 Even for input voltages that are less than 1000 V, the effect will persist until the input resistance temperature falls.
- until the input resistance temperature falls. For voltages in excess of 600 V, add the following to the phase
- difference accuracy: - 500 Hz < f ≤ 5 kHz: ±0.3°
- 5 kHz < f ≤ 20 kHz: ±0.5° 20 Hz < f ≤ 200 kHz: ±1°

Measurement parameters	Accuracy	
Apparent power	Voltage accuracy + current accuracy ±10 dgt.	
Reactive power	Apparent power accuracy +	
	$(\sqrt{2.69 \times 10^{-4} \times f} + 1.0022 - \lambda^2 - \sqrt{1 - \lambda^2}) \times 100\% \text{ f.s.}$	
Power factor		
Waveform peak	Voltage/current RMS accuracy ±1% f.s. (f.s.: apply 300% of range)	

 $f\colon kHz; \ \varphi\colon Display \ value for \ voltage/current phase \ difference;$ $<math display="inline">\lambda\colon Display \ value for \ power factor$

Effects of temperature and humidity

A. Display varies for power factor

Add the following to the voltage, current, and active power accuracy within the range of 0°C to 20°C or 26°C to 40°C:
±0.01% rdg./°C (add 0.01% f.s./°C for DC measured values)
For current and active power when using Probe 2, ±0.02% rdg./°C (add 0.05% f.s./°C for DC measured values)
Under conditions of 60% RH or greater:
Add ±0.0006 x humidity (%RH] x f [kHz]% rdg. to the voltage and active power accuracy.
Add ±0.0006 x humidity (%RH] x f [kHz]% rdg. to the phase difference.

50 Hz/60 Hz: 100 dB or greater (when applied between the voltage

inputterminals and the enclosure)

100 kHz: 80 dB or greater (reference value)

Defined for CMRR when the maximum input voltage is applied for all Effects of commonmode voltage measurement ranges.

Effects of external magnetic fields ±1% f.s. or less (in a magnetic field of 400 A/m, DC or 50 Hz/ 60 Hz)

 $\pm \left(1 - \frac{\cos(\phi + \text{phase difference accuracy})}{\cos(\phi)}\right) \times 100\% \text{rdg}.$ Φ of other than ±90°: Effects of power factor

φ of ±90° ±cos (φ + phase difference accuracy) × 100% f.s

Frequency measurement

Number of measurement channels	Max. 6 channels (f1 to f6), based on the number of input channels		
Measurement source	Select from U/I for each connection.		
Measurement method	Reciprocal method + zero-cross sampling value correction Calculated from the zero-cross point of waveforms after application of the zero-cross filter.		
Measurement range	0.1 Hz to 2 MHz (Display shows 0.00000 Hz or Hz if measurement is not possible.)		
Accuracy	±0.01Hz (Only when measuring 45-66 Hz with a minimum measurement interval of 50 ms and sine input of at least 50% relative to the voltage range when measuring the voltage frequency.) ±0.05% rdg ± 1 dgt. (other than the conditions mentioned above, when the sine wave is at least 30% relative to the measurement source's measurement range)		
Display format	0.10000 Hz to 9.99999 Hz, 9.9000 Hz to 99.9999 Hz, 99.000 Hz to 999.999 Hz, 0.99000 kHz to 9.99999 kHz, 9.9000 kHz to 99.9999 kHz, 99.000 kHz to 999.999 kHz, 0.99000 MHz to 2.00000 MHz		

Integration measurement

•					
Measurement modes	Select RMS or DC for each connection (DC mode can only be selected when using an AC/DC sensor with a 1P2W connection).				
Measurement parameters	Current integration (lh+, lh-, lh), active power integration (WP+, WP-, WP) lh+ and lh- are measured only in DC mode. Only lh is measured in RMS mode.				
	Digital calculation based on current and active power values				
Measurement method	DC mode Every sampling interval, current values and instantaneous power values are integrated separately for each polarity.				
	RMS mode The current RMS value and active power value are integrated for each measurement interval. Only active power is integrated separately for each polarity.				
Display resolution	999999 (6 digits + decimal point), starting from the resolution at which 1% of each range is f.s.				
Measurement range	0 to ±9999.99 TAh/TWh				
Integration time	10 sec. to 9999 hr. 59 min. 59 sec.				
Integration time accuracy	±0.02% rdg. (0°C to 40°C)				
Integration accuracy	±(current or active power accuracy) ±integration time accuracy				
Backup function	None				

Harmonics measurement

Number of measurement channels	Max. 6 channels, based on the number of built-in channels			
Synchronization source	Based on the synchronization source setting for each connection.			
Measurement modes Select from IEC standard mode or wideband mode (setting applic channels).				
Measurement parameters	Harmonic voltage RMS value, harmonic voltage content ratio, harmonic voltage phase angle, harmonic current RMS value, harmonic current content ratio, harmonic current phase angle, harmonic active power, harmonic power content ratio, harmonic voltage/current phase difference, total voltage harmonic distortion, total current harmonic distortion, voltage unbalance ratio, current unbalance ratio			
FFT processing word length	32 bits			
Antialiasing	Digital filter (automatically configured based on synchronization frequency)			
Window function	Rectangular			
Grouping	OFF / Type 1 (harmonic sub-group) / Type 2 (harmonic group)			
THD calculation method	THD_F / THD_R (Setting applies to all connections.) Select calculation order from 2nd order to 100th order (however, limited to the maximum analysis order for each mode).			

(1) IEC standard mode

Measurement method	Zero-cross synchronization calculation method (same window for each synchronization source) Fixed sampling interpolation calculation method with average thinning in window IEC 61000-4-7:2002 compliant with gap overlap
Synchronization frequency range	45 Hz to 66 Hz
Data update rate	Fixed at 200 ms.
Analysis orders	0th to 50th
Window wave number	When less than 56 Hz, 10 waves; when 56 Hz or greater, 12 waves

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Number of FFT points		4096 poi	nts			
Accuracy		Frequency		Harmonic voltage and current	Harmonic power	Phase difference
		DC (0th order)		±0.1% rdg. ±0.1% f.s.	±0.1% rdg. ±0.2% f.s.	
		45 Hz ≤ f ≤ 66 Hz		±0.2% rdg. ±0.04% f.s.	±0.4% rdg. ±0.05% f.s.	±0.08°
	Accuracy	66 Hz < f ≤ 440 Hz		±0.5% rdg. ±0.05% f.s.	±1.0% rdg. ±0.05% f.s.	±0.08°
		440 Hz < f	≤1 kHz	±0.8% rdg. ±0.05% f.s.	±1.5% rdg. ±0.05% f.s.	±0.4°
		1 kHz < f ≤ 2.5 kHz		±2.4% rdg. ±0.05% f.s.	±4% rdg. ±0.05% f.s.	±0.4°
		2.5 kHz < f	≤ 3.3 kHz	+6% rdg. +0.05% f.s.	±10% rda, ±0.05% f.s.	+0.8°

\$3.3 kHz ±6% r0g; ±0.05% t.8. ±1.0% r0g; ±0.05% t.8. ±0.8% Unit for f in accuracy calculations as mentioned in the table above: kHz Power is defined for a power factor of 1. Accuracy specifications are defined for fundamental wave input that is greater than or equal to 50% of the range. Add the current sensor accuracy to the above accuracy figures for current, active

power, and phase difference. Add $\pm 0.02\%$ rdg. for voltage and active power at or above 1000 V (however,

figures are reference values). Even for input voltages that are less than 1000 V, the effect will persist until the

input resistance temperature falls.

(2) Wideband mode

	Zero-cross synchronization calculation method (same window of synchronization source) with gaps Fixed sampling interpolation calculation method						
Synchronization frequency range	0.1 Hz to 300 kHz						
Data update rate	Fixed at 50 ms.						
	Frequency	Window wave number	Maximum analysis order				
	0.1 Hz ≤ f < 80 Hz	1	100th				
	0011 (40011		40011				

	Frequency	Window wave number	Maximum analysis order
	0.1 Hz ≤ f < 80 Hz	1	100th
	80 Hz ≤ f < 160 Hz	2	100th
	160 Hz ≤ f < 320 Hz	4	60th
	320 Hz ≤ f < 640 Hz	2	60th
Maximum analysis order and	640 Hz ≤ f < 6 kHz	4	50th
Window wave number	6 kHz ≤ f < 12 kHz	2	50th
Willdow wave fluilibei	12 kHz ≤ f < 25 kHz	4	50th
	25 kHz ≤ f < 50 kHz	8	30th
	50 kHz ≤ f < 101 kHz	16	15th
	101 kHz ≤ f < 201 kHz	32	7th
	201 kHz ≤ f ≤ 300 kHz	64	5th

The instrument provides phase zero-adjustment functionality using keys or Phase zero-adjustment communications commands (only available when the synchronization source is set to Ext). ver

	00110 2							
Accuracy					r voltage (wing table		active	powe

Frequency	Harmonic voitage and current	Harmonic power	Phase difference
DC	±0.1% f.s.	±0.2% f.s.	-
0.1 Hz ≤ f < 30 Hz	±0.05% f.s.	±0.05% f.s.	±0.1°
30 Hz ≤ f < 45 Hz	±0.1% f.s.	±0.2% f.s.	±0.1°
45 Hz ≤ f ≤ 66 Hz	±0.05% f.s.	±0.1% f.s.	±0.1°
66 Hz < f ≤ 1 kHz	±0.05% f.s.	±0.1% f.s.	±0.1°
1 kHz < f ≤ 10 kHz	±0.05% f.s.	±0.1% f.s.	±0.6°
10 kHz < f ≤ 50 kHz	±0.2% f.s.	±0.4% f.s.	±(0.020×f)° ±0.5°
50 kHz < f ≤ 100 kHz	±0.4% f.s.	±0.5% f.s.	±(0.020×f)° ±1°
$100 \text{ kHz} < f \le 500 \text{ kHz}$	±1% f.s.	±2% f.s.	±(0.030×f)° ±1.5°
$500 \text{ kHz} < \text{f} \leq 900 \text{ kHz}$	±4% f.s.	±5% f.s.	±(0.030×f)° ±2°

Unit for f in accuracy calculations as mentioned in the table above: kHz
The figures for voltage, current, power, and phase difference for frequencies in excess of 300 kHz are reference values.
When the fundamental wave is outside the range of 16 Hz to 850 Hz, the figures for voltage, current, power, and phase difference for frequencies other than the fundamental wave are reference values.
When the fundamental wave is within the range of 16 Hz to 850 Hz, the figures for voltage, current, power, and phase difference in excess of 6 kHz are reference values.

Accuracy values for phase difference are defined for input for which the voltage and current for the same order are at least 10% f.s.

Waveform recording

Number of measurement channels	Voltage and current waveforms Motor waveforms *	Max. 6 channels (based on the number of installed channels) Max. 2 analog DC channels + max. 4 pulse channels				
	1 Mword x ((voltage + current) x max. 6 channels + motor waveforms)					
Recording capacity	Fixed to 1 Mword when the numb	er of channels is low.				
3, ,	Motor waveforms: Motor analysis No memory allocation function	and D/A-equipped models only				
Waveform resolution	16 bits (Voltage and current wave	eforms use the upper 16 bits of the 18-bit A/D.)				
Sampling speed	Voltage and current waveforms Motor waveforms * Motor pulse *	Always 5 MS/s Always 50 kS/s (analog DC) Always 5 MS/s				
Compression ratio	(5 MS/s, 2.5 MS/s, 1 MS/s, 500 kS	1/1, 1/2, 1/5, 1/10, 1/20, 1/50, 1/100, 1/200, 1/500 (5 MS/s, 2.5 MS/s, 1 MS/s, 500 kS/s, 250 kS/s, 50 kS/s, 50 kS/s, 25 kS/s, 10 kS/s) However, motor waveforms* are only compressed at 50 kS/s or less.				
Recording length	1 kWord / 5 kWord / 10 kWord / 5	0 kWord / 100 kWord / 500 kWord / 1 Mword				
Storage mode	Peak-to-peak compression or sin	nple thinning				
Trigger mode	When FFT analysis is enabled in	SINGLE or NORMAL (with forcible trigger setting) When FFT analysis is enabled in NORMAL mode, the instrument enters trigger standby and waits for FFT calculations to complete.				
Pre-trigger	0% to 100% of the recording leng	gth, in 10% steps				
Trigger source	Voltage and current waveform, waveform after voltage and current zero-cross filter, manual, motor waveform*, motor pulse*					
Trigger slope	Rising edge, falling edge					
Trigger level	±300% of the range for the waveform, in 0.1% steps					
Trigger detection method	Trigger source: Voltage and current zero pulse (motor D/A-equipper Trigger slope: Rising edge, Trigger level: ±300% of the C2 Event trigger Detects the trigger based or parameter selected for D/A or Specifically, trigger detect operations performed on the operator has precedence over Event: These conditions are the conditions of the c	erange for the waveform, in 0.1% steps in fluctuations in the value of the measurement utput. Iton conditions are set using OR and AND is four events defined below. Note that the AND is the Compensator. If the OR operator. If a D/A output the parameter (D/A13 to D/A20), an inequality sign a value (0.00000 to 999999T). If the OR operator operator operator of the OR operator operato				

*Motor waveform and motor pulse: Motor Analysis and D/A-equipped models only

FFT analysis

J -	
Measurement channel	Voltage-Current Waveform - 1 channel (selected from input channels) Motor Waveform - Analog DC Analysis performed only when FFT screen is displayed
Calculation type	RMS spectrum
Number of FFT points	1,000, 5,000, 10,000 or 50,000 points
FFT processing word length	32 bits
Analysis position	Any desired position among the waveform record data
Antialiasing	Automatic Digital Filter (during simple thinning mode) None (During Peak-Peak compression mode, use the Max value and perform FFT)
Window function	Rectangular/Hanning/Flat-top
Max. analysis frequency	Linked with compression ratio of waveform records. 2 MHz, 1 MHz, 400 kHz, 200 kHz, 100 kHz, 40 kHz, 20 kHz, 10 kHz, 20 kHz, 10 kHz or 4 kHz / 20 kHz, 10 kHz, or 4 kHz during analog DC input (Mentioned above frequency - frequency resolution) becomes the maximum analysis frequency
FFT peak value display	Compute 10 frequencies and voltage-current peak value levels (local maximum value) each starting from the top, ordered by level / For FFT calculation results, recognize as the peak value when the data on both sides is lower than the original data

Motor Analysis (PW6001-11 to -16 only)

Number of input channels	4 channels:	CH A CH B CH C	Analog DC input / Frequency input / Pulse input Analog DC input / Frequency input / Pulse input Pulse input Pulse input				
Operating mode	Single, dual,	Single, dual, or independent input					
Input terminal profile	Isolated BNC	solated BNC connectors					
Input resistance (DC)	1 MΩ ±50 kΩ	1 MΩ ±50 kΩ					
Input method	Function-isol	Function-isolated input and single-end input					
Measurement parameters	Voltage, torqu	Voltage, torque, rpm, frequency, slip, motor power					
Maximum input voltage	±20 V (analog	±20 V (analog DC and pulse operation)					
Additional conditions for guaranteed accuracy	Input: Terminal-to-ground voltage of 0 V, after zero-adjustment						
(1) Analog DC inpo	ut (CH A/C	HB)					
Measurement range	±1 V / ±5 V / ±10 V						

(1) Analog DC Inpi	JL (CH A/CH B)
Measurement range	±1 V / ±5 V / ±10 V
Effective input range	1% to 110% f.s.
Sampling	50 kHz, 16 bits
Response speed	0.2 ms (when LPF is OFF)
Measurement method	Simultaneous digital sampling, zero-cross synchronization calculation method
Weasurement method	(averaging between zero-crosses)
Measurement accuracy	±0.05% rdg. ±0.05% f.s.
Temperature coefficient	±0.03% f.s./°C
Effects of common- mode voltage	$\pm 0.01\%$ f.s. or less with 50 V applied between the input terminals and the enclosure (DC / 50 Hz / 60 Hz)
LPF	OFF (20 kHz) / ON (1 kHz)
Display range	From the range's zero-suppression range setting to ±150%
Zero-adjustment	Voltage ±10% f.s., zero-correction of input offsets that are less
(2) Frequency input	(CH A/CH B)

Detection level	Low: 0.5 V or less; high: 2.0 V or more
Measurement frequency band	0.1 Hz to 1 MHz (at 50% duty ratio)
Minimum detection width	0.5 μ s or more
Measurement accuracy	±0.05% rdg. ±3 dgt.
Display range	1.000 kHz to 500.000 kHz
(3) Pulse input (CH	A / CH B / CH C / CH D)
Detection level	Low: 0.5 V or less; high: 2.0 V or more

Measurement frequency band	0.1 Hz to 1 MHz (at 50% duty ratio)
Minimum detection width	0.5 μ s or more
Pulse filter	OFF / Weak / Strong (When using the weak setting, positive and negative pulses of less than 0.5 µs are ignored. When using the strong setting, positive and negative pulses of 5 µs are ignored.)
Measurement accuracy	±0.05% rdg. ±3 dgt.
Display range	0.1 Hz to 800.000 kHz
Unit	Hz / r/min.
Frequency division setting range	1~60000
Rotation direction detection	Can be set in single mode (detected based on lead/lag of CH B and CH C).
Mechanical angle origin detection	Can be set in single mode (CH B frequency division cleared at CH D rising edge).

D/A output (PW6001-11 to -16 only)

(77
Number of output channels	20 channels	
Output terminal profile	D-sub 25-pin conn	ector x 1
Output details	(select from basi	een waveform output and analog output ic measurement parameters). .is fixed to CH1 to CH12.
D/A conversion resolution	16 bits (polarity + 1	15 bits)
Output refresh rate	Analog output Waveform output	10 ms / 50 ms / 200 ms (based on data update rate for the selected parameter) 1 MHz
Output voltage	Analog output Waveform output	±5 V DC f.s. (max. approx. ±12 V DC) Switchable between ±2 V f.s. and ±1 V f.s., crest factor of 2.5 or greater. Setting applies to all channels.
Output resistance	100 Ω ±5 Ω	
	Analog output	Output measurement parameter measurement accuracy ±0.2% f.s. (DC level)
Output accuracy	Waveform output	$\label{eq:measurement accuracy \pm 0.5\% f.s. (at \pm 2 V f.s.)} \\ or \pm 1.0\% f.s. (at \pm 1 V f.s.) \\ (RMS value level, up to 50 kHz)$
Temperature coefficient	±0.05% f.s./°C	

Display section

Display characters	English, Japanese, Chinese (simplified)	
Display		or LCD (800 × 480 dots) light and analog resistive touch panel
Display value resolution	999999 count (including integration values)	
Display refresh rate	Measured values Waveforms	Approx. 200 ms (independent of internal data update rate) When using simple averaging, the data update rate varies based on the number of averaging iterations. Based on display settings
	wavelullis	Dased on display settings

External interface

(1) USB flash drive interface

Connector	USB Type A connector x 1
Electrical specifications	USB 2.0 (high-speed)
Power supplied	Max. 500 mA
Supported USB flash drives	USB Mass Storage Class compatible
Recorded data	Save/load settings files Save measured values/automatic recorded data (CSV format) Copy measured values/recorded data (from internal memory) Save waveform data, save screenshots (compressed BMP format)

(2) LAN interface

Connector	RJ-45 connector x 1
Electrical specifications	IEEE 802.3 compliant
Transmission method	10Base-T / 100Base-TX / 1000Base-T (automatic detection)
Protocol	TCP/IP (with DHCP function)
Functions	HTTP server (remote operations) Dedicated port (data transferring, command control) FTP server (file transferring)

(3) GP-IB interface

	IEEE 488.1 1987 compliant developed with reference to IEEE 488.2 1987
method	Interface functions: SH1, AH1, T6, L4, SR1, RL1, PP0, DC1, DT1, C0
Addresses	00 to 30
Functions	Command control

(4) RS-232C interface

Connector	D-sub 9-pin connector x 1, 9-pin power supply compatible, also used for external control
Communication	RS-232C, EIA RS-232D, CCITT V.24, and JIS X5101 compliant
method	Full duplex, start stop synchronization, data length of 8, no parity, 1 stop bit
Flow control	Hardware flow control ON/OFF
Communications speed	9,600 bps / 19,200 bps / 38,400 bps / 57,600 bps / 115,200 bps / 230,400 bps
Functions	Command control LR8410 Link supported (dedicated connector is required) Used through exclusive switching with external control interface

(5) External control interface

	Connector	D-sub 9-pin connector x 1, 9-pin power supply compatible, also used for RS-232C
	Power supplied	OFF/ON (voltage of +5 V, max. 200 mA)
	Electrical specifications	0/5 V (2.5 V to 5 V) logic signals or contact signal with terminal shorted or open
		Same operation as the [START/STOP] key or the [DATA RESET] key on the
	Functions	control panel
		Used through exclusive switching with RS-232C

(6) Two-instrument synchronization interface

(b) Two instrument synomenation interface		
Connector	SFP optical transceiver, Duplex-LC (2-wire LC)	
Optical signal	850 nm VCSEL, 1 Gbps	
Laser class	Class 1	
Fiber used	50/125 μm multi-mode fiber equivalent, up to 500 m	
Functions	Sends data from the connected secondary instrument to the primary instrument,	

Auto-range function

Functions	The voltage and current ranges for each connection are automatically changed in response to the input.
Operating mode	OFF/ON (selectable for each connection)
Auto-range breadth	Broad/ narrow (applies to all channels) Broad The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 110% f.s. The range is lowered by two if all RMS values for the connection are less than or equal to 10% f.s. Narrow The range is increased by one if the peak value is exceeded for the connection or if there is an RMS value that is greater than or equal to 105% f.s. The range is lowered by one if all RMS values for the connection are less than or equal to 40% f.s. Voltage range changes when A-Y conversion is enabled are determined by multiplying the range by f.—1

Time control function

Timer control	OFF, 10 sec. to 9999 hr. 59 min. 59 sec. (in 1 sec. steps)
Actual time control	OFF, start time/stop time (in 1 min. steps)
Intervals	OFF / 10 ms / 50 ms / 200 ms / 500 ms / 1 sec. / 5 sec. / 10 sec. / 15 sec. / 30 sec. 1 min. / 5 min. / 10 min. / 15 min. / 30 min. / 60 min.

Hold function

Hold	Stops updating the display with all measured values and holds the value currently being displayed. Used exclusively with the peak hold function.
Peak hold	Updates the measured value display each time a new maximum value is set. Used exclusively with the hold function.

Calculation function

(1) Rectifier

Functions	Selects the voltage and current values used to calculate apparent and reactive power and power factor.						
Operating mode	RMS/mean (Car	n be seled	cted for eac	h connectio	on's volta	ge and cu	rent.)
(2) Scaling							
VT (PT) ratio	OFF/ 0.00001 to	9999.99	1				
CT ratio	OFF/ 0.01 to 99	99.99					
(3) Averaging (AV	G)						
Functions	All instantaneou	ıs measu	red values,	including h	armonics	, are avera	aged.
Operating mode	OFF / Simple av	eraging /	Exponentia	al averagin	9		
Operation	Exponential ave	o T a eraging D d a g operation	efined by t veraging re- n, averaged o	s updated. date rate rations. onentially a he data u sponse rate data is used	is length averaged pdate ra e. for all ana	using a le and the	time const e exponen
	iteratio		5	10	20	50	100
Number of simple averaging iterations	Data	10 ms	50 ms	100 ms	200 ms	500 ms	1 sec.
averaging iterations	update rate	50 ms	250 ms	500 ms	1 sec.	2.5 sec.	5 sec.
	.,	200 ms	1 sec.	2 sec.	4 sec.	10 sec.	20 sec.
Exponential averaging response rate	Setting			FAST	N	ИID	SLOW
	Data update rate		10 ms	0.1 sec.		sec.	5 sec.
			50 ms	0.5 sec		sec.	25 sec.
			200 ms	2.0 sec	. 16	sec.	100 sec.

(4) User-defined calculations

Functions	User-specified basic measurement parameters are calculated using the specified calculation formulas.
Calculated items	Four basic measured items or constants with a maximum of 6-digits; operators are four-arithmetic operators. UDFn = ITEM1 □ ITEM2 □ ITEM3 □ ITEM4 ITEMn: basic measured item, or constant of up to 6 digits □: any one of +, -, *, or f UDFn can also be selected for ITEMn, with calculations performed in the order of n. The functions that can be selected and calculated in regards to each ITEMn are as follows: neg, sin, cos, tan, sort, abs, log10 (common logarithm), log (logarithm), exp, asin, acos, atan, sinh, cosh, tanh When a UDFn with an n higher than the current UDF is encounted, previously calculated values are used.
Number of allowed calculations	16 formulas (UDF1 to UDF16)
Maximum value setting	Set for each UDFn in the range 1.000 μ to 100.0 T / Functions as a UDFn range
Unit	Up to 6 characters in ASCII for each UDFn

Calculated items	Active power value (P), fundamental wave active power (Pfnd), and motor power (Pm) (Motor Analysis and D/A-equipped models only) for each channel and connection
Number of calculations that can be performed	Four each for efficiency and loss
Formula	Calculated items are specified for Pin(n) and Pout(n) in the following format: Pin = Pin1 + Pin2 + Pin3 + Pin4, Pout = Pout1 + Pout2 + Pout3 + Pout4 $\eta = 100 \times \frac{ Pout1 }{ Pin1 } \cdot Loss = Pin1 \cdot Pout1 $

(6) Power formula selection

Functions	Selects the reactive power, power factor, and power phase angle formulas.			
Formula	TYPE1 /TYPE2 /TYPE3 TYPE1 Compatible with TYPE1 as used by the Hioki 3193 and 3390. TYPE2 Compatible with TYPE2 as used by the Hioki 3192 and 3193. TYPE3 The sign of the TYPE1 power factor and power phase angle are used as the active power signs.			

(7) Delta conversion

Functions	∆-Y When using a 3P3W3M or 3V3A connection, converts the line voltage waveform to a phase voltage waveform using a virtual neutral point. ∆ When using a 3P4W connection, converts the phase voltage waveform to a line voltage waveform. Voltage RMS values and all voltage parameters, including harmonics, are calculated, using the post-conversion voltage.

(8) Current sensor phase shift calculation

Functions	Compensates the current sensor's harmonic phase characteristics using calculations.
Compensation value settings	Compensation points are set using the frequency and phase difference. Frequency 0.1 kHz to 999.9 kHz (in 0.1 kHz steps) Phase difference 0.00° to ±90.00° (in 0.01° intervals) However, the difference in time calculated from the frequency phase difference can be up to 98 ps in 0.5 nis intervals

Display function

(1) Connection confirmation screen

Functions	Displays a connection diagram and voltage and current vectors based on the selected measurement lines. The ranges for a correct connection are displayed on the vector display so that the connection can be checked.
Mode at startup	User can select to display the connection confirmation screen at startup (startup screen setting).
Simple settings	Commercial power supply / Commercial power supply high-resolution HD / DC / DC high-resolution HD / PWM / High-frequency / Low Power factor/ Other

(2) Vector display screen

Functions	Displays a connection-specific vector graph along with associated level values and phase angles.

(3) Numerical display screen

Basic by connection Displays measured values for the measurement lines and motors combined in the connection. There are four measurement line patterns: U, I, P, and Integ. Creates a numerical display for the measurement parameters that the user has selected from all basic measurement parameters in the location selected by the user. There are 4. 8. 1.6. and 32-display on thems.	Functions	Displays power mea instrument channels.	sured values and motor measured values for up to six
There are 4, 0, 10, and 02 display patterns.	Display patterns	,	motors combined in the connection. There are four measurement line patterns: U, I, P, and Integ. Creates a numerical display for the measurement parameters that the user has selected from all basic measurement

(4) Harmonic display screen

Display patterns Display list: Specified channels as a bar graph. Displays numerical values for user-specified parame	Functions	Displays harmonic measured values on the instrument's screen.		
and doct opcomed charmers.	Display patterns	., .,	Displays harmonic measurement parameters for user specified channels as a bar graph. Displays numerical values for user-specified parameter and user-specified channels.	

(5) Waveform display screen

Functions	Displays the voltage and current waveforms and motor waveform.
Display patterns	All-waveform display, waveform + numerical display

Simplified Graph Function (1) D/A Monitor Graph

(1) Bit World Craph	
Functions	Graph measured values chosen as D/A output items in chronological order Illustrated waveforms are Peak-Peak compressed by setting time axis to data at data update rate, and data is not recorded.
Operations	Start and stop drawing with the RUN/STOP button Illustrate the displayed value during hold and peak hold Illustrated data is cleared when Clear button is pressed during changes in settings related to measured values of range and D/A output items
Number of illustrated items	Maximum of 8 items
Illustrated items	Operates simultaneously with D/A output items from CH13 to CH20 settings
Time axis	10 ms/dot to 48 min/dot (Cannot be selected below the data update rate)
Vertical axis	Autoscaling (operates to fit data on screen within screen display range with time axis) Manual (user sets displayed maximum value and minimum value)

(2) X-Y Plot

Functions	Select horizontal and vertical axis items from fundamental measurement items and display X-Y graph Dot illustrations are done at data update rate, and data is not recorded Illustration data can be cleared / a total of two combinations of graphs can be displayed: X1-Y1 or X2-Y2 Gauge display, displayed max value and min value settings are allowed X1, Y1, X2, and Y2 operate in synchronization with D/A output item settings for CH13, 14, 15, and 16 respectively
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Automatic save function

Functions	Saves the specified measured values in effect for each interval.	
Save destination	OFF / Internal memory / USB flash drive	
Saved parameters	User-selected from all measured values, including harmonic measured values	
Maximum amount of saved data	Internal memory 64 MB (data for approx. 1800 measurements) USB flash drive Approx. 100 MB per file (automatically segmented) × 20 files	
Data format	CSV file format	

Manual save function

(1) Measurement data

Functions	The [SAVE] key saves specified measured values at the time it is pressed. Comment text can be entered for each saved data point, up to a maximum of 20 alphanumeric characters. *The manual save function for measurement data cannot be used while automatic save is in progress.
Save destination	USB flash drive
Saved parameters	User-selected from all measured values, including harmonic measured values
Data format	CSV file format

(2) Waveform data

Functions	(Within touch panel) Use Save Waveforms Button to save waveform data during that session Input comments for each set of saved data "Cannot be operated when waveform data is invalid during storage and automatic saving
Save destination	USB flash drive - Assign destinations for saved data
Comment entry	OFF/ON - up to 40 letters/symbols
Data format	CSV file format (read-only attribute included), binary file format (BIN format)

(3) Screenshots

Functions	The [COPY] key saves a screenshot to the save destination. *This function can be used at an interval of 1 sec or more while automatic saving is in progress.
Save destination	USB flash drive
Comment entry	OFF / Text / Handwritten When set to [Text], up to 40 alphanumeric characters When set to [Handwritten], hand-drawn images are pasted to the screen.
Data format	Compressed BMP

(4) Settings data

Functions	Saves settings information to the save destination as a settings file via functionality provided on the File screen. In addition, previously saved settings files can be loaded and their settings restored on the File screen. However, language and communications settings are not saved.
Save destination	USB flash drive

(5) FFT data

Functions	(Within touch panel) Use Save FFT Spectrum button to save waveform data during that session Input comments for each set of saved data *Cannot be operated when waveform data is invalid during storage and automatic saving
Save destination	USB flash drive - Assign destinations for saved data
Comment entry	OFF/ON - up to 40 letters/symbols
Data format	CSV file format (with read-only attribute set)

Two-instrument synchronization function

Functions	which performs calculations and displays the results. In numerical synchronization mode, the primary instrument operates as a powe meter with up to 12 channels. In waveform synchronization mode, the primary instrument operates while synchronizing up to three channels from the secondary instrument at the waveform level.	
Operating mode		/ Waveform synchronization be selected when the data update rate is 10 ms. tes only when primary device has more than 3
Synchronized items	,	Data update timing, start/stop/data reset Voltage/current sampling timing
Synchronization delay	Numerical synchronization mode Waveform synchronization mode	'
	Numerical synchronization mode	Basic measurement parameters for up to six channels (including motor data)
Transfer items	Waveform synchronization mode	Voltage/current sampling waveforms for up to three channels (not including motor data). However, the maximum number of channels is limited to a total of six, including the primary instrument's channels.

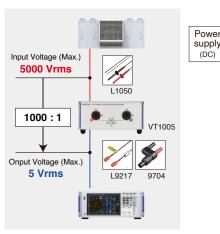
General Specifications

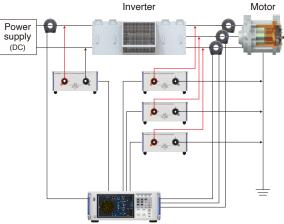
Operating environment	Indoors at an elevation of up to 2000 m in a Pollution Level 2 environment	
Storage temperature and humidity	-10°C to 50°C, 80% RH or less (no condensation)	
Operating temperature and humidity	0°C to 40°C, 80% RH or less (no condensation)	
Dielectric strength	5.0 Hz/60 Hz 5.4 kV rms AC for 1 min. (sensed current of 1 mA) Between voltage input terminals and instrument enclosure, and between current sensor input terminals and interfaces 1 kV rms AC for 1 min. (sensed current of 3 mA) Between motor input terminals (Ch. A, Ch. B, Ch. C, and Ch. D) and the instrument enclosure	
Standards	Safety EN61010 EMC EN61326 Class A	
Rated supply voltage	100 V AC to 240 V AC, 50 Hz/ 60 Hz	
Maximum rated power	200 VA	
External dimensions	Approx. 430 mm (16.93 in)W x 177 mm (6.97 in)H x 450 mm (17.72 in)D (excluding protruding parts)	
Mass	Approx. 14 kg (49.4 oz) (PW6001-16)	
Backup battery life	Approx. 10 years (reference value at 23°C) (lithium battery that stores time and setting conditions)	
Product warranty period	3 year	
Guaranteed accuracy period	6 months (1-year accuracy = 6-month accuracy × 1.5)	
Accuracy guarantee conditions	Accuracy guarantee temperature and humidity range: 23°C ±3°C, 80% RH or less Warm-up time: 30 min. or more	
Accessories	Instruction manual x 1, power cord x 1, D-sub 25-pin connector x 1 (PW6001-1x only)	

Other functions

Clock function	Auto-calendar, automatic leap year detection, 24-hour clock
Actual time accuracy	When the instrument is on, ±100 ppm; when the instrument is off, within ±3 sec./day (25°C)
Sensor identification	Current sensors connected to Probe1 are automatically detected.
Zero-adjustment function	After the AC/DC current sensor's DEMAG signal is sent, zero-correction of the voltage and current input offsets is performed.
Touch screen correction	Position calibration is performed for the touch screen.
Key lock	While the key lock is engaged, the key lock icon is displayed on the screen.

Measure High Voltages of up to 5000 V





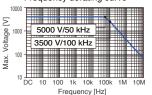
The AC/DC High Voltage Divider VT1005 divides and outputs voltages of up to 5000 V. With the PW6001, the VT1005 can accurately measure high voltages of up to 5000 V.



AC/DC HIGH VOLTAGE **DIVIDER VT1005**

Frequency derating curve



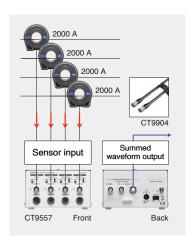


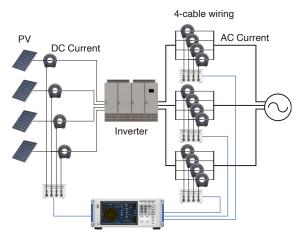
Frequency characteristics (typical value) 1k 10k 100k Frequency [Hz]

VT1005 specifications

5000 V rms, ±7100 V peak (Provided this falls within the frequency derating curve illustrated)
No measurement category: 5000 V AC/DC (7100 V peak, Anticipated transient overvoltage 0 V) Measurement category II: 2000 V AC/DC (Anticipated transient overvoltage 12000 V) Measurement category III: 1500 V AC/DC (Anticipated transient overvoltage 10000 V)
±0.08% (DC), ±0.04% (50 Hz/60 Hz), ±0.17% (50 kHz)
Band where amplitude falls within ±0.1% range: 200 kHz (typical) Band where phase falls within ±0.1° range: 500 kHz (typical) (15)
DC to 4 MHz (Amplitude and phase accuracy specified up to 1 MHz)
1000 : 1
50 Hz/60 Hz: 90 dB (typical), 100 kHz: 80 dB (typical)
-10°C to 50°C (14°F to 122°F), 80% RH or less (non-condensing)
100 V to 240 V AC (50/60 Hz)
Approx. 195.0 × 83.2 × 346.0 mm (7.68 × 3.28 × 13.62 in.)
Approx. 2.2 kg (77.6 oz.)
Differential input
- L1050-01 Voltage Cord (1.6 m/ 5.25 ft) - L9217 Connection Cord (insulated BNC, 1.6 m/ 5.25 ft) - 9704 Conversion Adapter (insulated-female BNC-to-banana plug) - Power cord

Measure Large Currents of up to 8000 A





The Sensor Unit CT9557 adds and outputs current sensor output from multi-wire lines. With the PW6001, the CT9557 can be used to accurately measure large currents of up to 8000 A (on a 4-wire line).



SENSOR UNIT CT9557

CT9557 specifications

Connectable current sensor	Current sensors are listed on p. 19 - p. 21.			
	DC	: ±0.06% ±0.03%		
	~ 1 kHz	: ±0.06% ±0.03%		
Summed waveform	~ 10 kHz	: ±0.10%. ±0.03%		
output accuracy ±(% of reading + % of full	~ 100 kHz	: ±0.20% ±0.10%		
scale)	~ 300 kHz	: ±1.0% ±0.20%		
354.5)	~ 700 kHz	: ±5.0% ±0.20%		
	~ 1 MHz	: ±10.0% ±0.50%		
Operating temperature and	-10°C to 50°C (14°F to 122°F),			
humidity	80% RH or less			
Power supply	100 V to 240 V AC (50	Hz/60 Hz)		
Output connector	HIOKI ME15W (male	connector)		
Dimensions (W x H x D)	Approx. 116 mm W × 67 mm H × 132 mm D			
Difficusions (W X 11 X D)	(approx. 4.57 in. W × 2.64 in. H × 5.20 in. D)			
Weight	Approx. 420 g (14.8 oz.)			
Included accessories	AC ADAPTER Z1002, Power cord			

Wiring	Current Using sensors	
Single-cable	1000 A	CT6876A CT6846A
or bundled wiring	2000 A	CT6877A
2-cable	2000 A	CT9557+CT6876A×2/ CT9557+CT6846A×2
wiring	4000 A	CT9557+CT6877A×2
3-cable	3000 A	CT9557+CT6876A×3/ CT9557+CT6846A×3
wiring	6000 A	CT9557+CT6877A×3/
4-cable	4000 A	CT9557+CT6876A×4/ CT9557+CT6846A×4
wiring	8000 A	CT9557+CT6877A×4



CONNECTION CABLE CT9904 Cable length: 1 m (3.28 ft) CT9904 required to connect to PW6001.

Current sensors High accuracy pass-through (connect to Probe1 input terminal)

		CT6877A,	CT6877A-1*2	CT6876A	, CT6876A-1* ²	CT6904A-2	CT6904A-3*2
Appearance		NEW		NEW		NEW Wideband 4 MHz	Build-to-order product CT6904A-2 CT6904A-3
R	ated current	2000	A AC/DC	1000	A AC/DC	800 A	AC/DC
Frequency band		DC to	o 1 MHz		DC to 1.5 MHz I: DC to 1.2 MHz	CT6904A-2: DC to 4 MHz CT6904A-3: DC to 2 MHz	
Di	ameter of measurable conductors	Max. φ 80	mm (3.14 in.)	Max. φ 3	6 mm (1.42 in.)	Max. φ 32	mm (1.25 in.)
\Box	0 1 (1)	DC	: ±0.06% ±0.038%	DC	: ±0.06% ±0.038%	DC	: ±0.050% ±0.037%
	Current (I) PW6001	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.028%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.028%	45 Hz ≤ f ≤ 65 Hz	: ±0.045% ±0.027%
	Combined*1	DC	: ±0.06% ±0.058%	DC	: ±0.06% ±0.058%	DC	: ±0.050% ±0.057%
	Active power (P)	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.038%	45 Hz ≤ f ≤ 66 Hz	: ±0.06% ±0.038%	45 Hz ≤ f ≤ 65 Hz	: ±0.045% ±0.037%
Ì		DC	: ±0.04% ±0.008%	DC	: ±0.04% ±0.008%	DC	: ±0.030% ±0.009%
		DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.1% ±0.02%	DC < f < 16 Hz	: ±0.2% ±0.025%
		16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 45 Hz	: ±0.1% ±0.025%
ac)	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor	45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 66 Hz	: ±0.04% ±0.008%	45 Hz ≤ f ≤ 65 Hz	: ±0.025% ±0.009%
Accuracy		66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	66 Hz < f ≤ 100 Hz	: ±0.05% ±0.01%	65 Hz < f ≤ 850 Hz	: ±0.05% ±0.009%
¥		100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.1% ±0.02%	850 Hz < f ≤ 1 kHz	: ±0.1% ±0.013%
ı		500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.2% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.4% ±0.025%
		1 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	1 kHz < f ≤ 5 kHz	: ±0.5% ±0.02%	5 kHz < f ≤ 10 kHz	: ±0.4% ±0.025%
		10 kHz < f ≤ 50 kHz	: ±1.5% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.5% ±0.02%	10 kHz < f ≤ 50 kHz	: ±1.0% ±0.025%
		50 kHz < f ≤ 100 kHz	: ±2.5% ±0.05%	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.05%	50 kHz < f ≤ 100 kHz	: ±1.0% ±0.063%
		100 kHz < f ≤ 700 kHz	: ±(0.025×f kHz)% ±0.05%	50 kHz < f ≤ 100 kHz	: ±3.0% ±0.05%	100 kHz < f ≤ 300 kHz	: ±2.0% ±0.063%
ı			_	100 kHz < f ≤ 1 MHz	: ±(0.03×f kHz)% ±0.05%	300 kHz < f ≤ 1 MHz	: ±5.0% ±0.063%
0	perating Temperature	-40°C to 85°C	(-40°F to 185°F)	-40°C to 85°	C (-40°F to 185°F)	-10°C to 50°C	(-14°F to 122°F)
М	aximum rated voltage to earth	CATI	II 1000 V	CAT	'III 1000 V	CATII	I 1000 V
Di	imensions		9.13") × 112D (4.41") mm 9.84 ft), CT6877A-1:10 m (32.81 ft)]		(4.41") × 50D (1.97") mm (9.84 ft), CT6876A-1:10 m (32.81 ft)]		(4.72") × 52D (2.05") mm (9.84 ft), CT6904A-3:10 m (32.81 ft)
М	ass		ox. 5 kg (176.4 oz.) x. 5.3 kg (187.0 oz.)* ²		rox. 970 g (34.2 oz.) ox. 1300 g (45.9 oz.) *2		rox. 1150 g (40.6 oz.) x. 1450 g (51.1 oz.) * ²
Derating properties		100	140°F (continuous)	22k	C (140°F) (continuous)	To Do	usercy densiting 800 A 800 A 8 at an ambient 6 at an ambient 6 at an ambient 6 at an ambient 8 at a an ambient 8 at a ambient 9 at a ambient 10 at

^{*1 ±(%} of reading + % of range), range is PW6001

To CT6877A-1, CT6876A-1, and CT6904A-3 have a 10 m cord. For the CT6876A-1, add ±0.00 x f kHz)% of the range for 20 A range or 40 A range;

CT697A-1, CT687A-1, CT687A-1, and CT6904A-3 have a 10 m cord. For the CT6876A-1, add ±0.00 x f kHz)% of the reading for amplitude accuracy and ±(0.015 x f kHz)% for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz. For the CT6877A-1, add $\pm (0.005 \times f \, kHz)$ % of the reading for amplitude accuracy and $\pm (0.015 \times f \, kHz)$ * for phase accuracy for frequencies of 1 kHz < f \leq 700 kHz. For the CT6904A-3, add $\pm (0.015 \times f \, kHz)$ % of the reading for amplitude accuracy for frequencies of 50 kHz < f \leq 1 MHz.



CT6904A/CT6904A-1: Add ±0.12% of the range for 10 A range or 20 A range; CT6875A/CT6875A-1: Add ±0.15% of the range for 10 A range or 20 A range;

CT6873/CT6873-01: Add ±0.15% of the range for 4 A range or 8 A range.

*4 The CT6904A-1, CT6875A-1, and CT6875A-1 have a 10 m cord. For the CT6904A-1, add ±(0.015 × f kHz)% of the reading for amplitude accuracy for frequencies of 50 kHz < f ≤ 1 MHz.

	CT6863-05		CT6872, CT6872-01*6		СТ6	CT6862-05		
Appearance				Wideband 10 MHz				
R	ated current	200 A	A AC/DC	50	A AC/DC	50 A	AC/DC	
F	requency band	DC to	500 kHz	DC	to 10 MHz	DC to	o 1 MHz	
D	iameter of measurable conductors	Max. φ 24	mm (0.94 in.)	Max. φ 2	4 mm (0.94 in.)	Max. φ 24	mm (0.94 in.)	
	PW6001 Current (I) Combined*5 Active power (P)	PW6001 accurac	cy + Sensor accuracy	DC : ±0.05% ±0.032% 45 Hz < f < 66 Hz : +0.05% +0.027%		PW6001 accurac	uracy + Sensor accuracy	
		DC	: ±0.05% ±0.01%	DC	: ±0.03% ±0.002%	DC	: ±0.05% ±0.01%	
		DC < f ≤ 16 Hz	: ±0.10% ±0.02%	DC < f ≤ 16 Hz	: ±0.1% ±0.01%	DC < f ≤ 16 Hz	: ±0.10% ±0.02%	
Š		16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%	16 Hz < f ≤ 45 Hz	: ±0.05% ±0.01%	16 Hz ≤ f < 400 Hz	: ±0.05% ±0.01%	
Accuracy		400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%	45 Hz < f ≤ 66 Hz	: ±0.03% ±0.007%	400 Hz ≤ f ≤ 1 kHz	: ±0.2% ±0.02%	
Acc	Sensor only (amplitude)	1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%	66 Hz < f ≤ 100 Hz	: ±0.04% ±0.01%	1 kHz < f ≤ 5 kHz	: ±0.7% ±0.02%	
	±(% of reading +% of full scale)	5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%	100 Hz < f ≤ 500 Hz	: ±0.06% ±0.01%	5 kHz < f ≤ 10 kHz	: ±1.0% ±0.02%	
	full scale is rated current of sensor	10 kHz < f ≤ 50 kHz	: ±2.0% ±0.02%	500 Hz < f ≤ 1 kHz	: ±0.1% ±0.01%	10 kHz < f ≤ 50 kHz	: ±1.0% ±0.02%	
		50 kHz < f ≤ 100 kHz	: ±5.0% ±0.05%	1 kHz < f ≤ 5 kHz	: ±0.15% ±0.02%	50 kHz < f ≤ 100 kHz	: ±2.0% ±0.05%	
		100 kHz < f ≤ 300 kHz	: ±10% ±0.05%	5 kHz < f ≤ 10 kHz	: ±0.15% ±0.02%	100 kHz < f ≤ 300 kHz	: ±5.0% ±0.05%	
		300 kHz < f ≤ 500 kHz	: ±30% ±0.05%	10 kHz < f ≤ 1 MHz	: ±(0.012×f kHz)% ±0.05%	300 kHz < f ≤ 700 kHz	: ±10% ±0.05%	
			_		_	700 kHz < f < 1 MHz	: ±30% ±0.05%	
С	perating Temperature	-30°C to 85°C	(-22°F to 185°F)	-40°C to 85°C (-40°F to 185°F), 80% RH or less		-30°C to 85°C (-22°F to 185°F)		
N	laximum rated voltage to earth	CATI	II 1000 V	CA ⁻	TIII 1000 V	CATII	I 1000 V	
D	imensions		3.94") × 53D (2.09") mm oprox. 3 m (9.84 ft.)	70W (2.76") × 110H (4.33") × 53D (2.09") mm Cable length [CT6872: 3 m (9.84 ft), CT6872-01:10 m (32.81 ft)]			3.94") × 53D (2.09") mm pprox. 3 m (9.84 ft.)	
N	lass	Approx. 35	50 g (12.3 oz.)	CT6873: approx. 370 g (13.1 oz.) CT6873-01: approx. 690 g (24.3 o.z) *6		Approx. 340 g (12.0 oz.)		
D	erating properties	Frequency deraing Frequency deraing Frequency deraing Frequency deraing Frequency deraing		Transport Tran		0500	uency derating	

 $^{^{\}star5}$ ±(% of reading + % of range) , range is PW6001

Custom cable lengths also available. Please inquire with your Hioki distributor.

Current sensors High accuracy clamp (connect to Probe1 input terminal)



^{*1 ±(%} of reading + % of range), range is PW6001

CT6872/CT6872-01: Add ±0.15% of the range for 1 A range or 2 A range.

^{*6} The CT6872-01 has a 10 m cord. For the CT6872-01, add ±(0.015 x f kHz)° for phase accuracy for frequencies of 1 kHz < f ≤ 1 MHz.

CT6846A: Add ±1% of the range for the 20 A range, ±0.5% of the range for the 40 A range, and ±0.1% of the range for the 100 A range. CT6845A/CT6844A: Add ±1% of the range for the 10 A range, ±0.5% of the range for the 20 A range, and ±0.1% of the range for the 50 A range.

		CT6843A	CT6841A	
Appearance		NEW	NEW	
Ra	ited current	200 A AC/DC	20 A AC/DC	
Fre	equency band	DC to 700 kHz	DC to 2 MHz	
Dia	ameter of measurable conductors	Max. φ 20 mm (0.79 in.)	Max. φ 20 mm (0.79 in.)	
	Current (I)	DC : ±0.22% ±0.05% 45 Hz ≤ f ≤ 66 Hz : ±0.22% ±0.04%	DC : ±0.22% ±0.08% 45 Hz ≤ f ≤ 66 Hz : ±0.22% ±0.04%	
	Combined*2 Active power (P)	DC : ±0.22% ±0.07% 45 Hz ≤ f ≤ 66 Hz : ±0.22% ±0.05%	DC : ±0.22% ±0.1% 45 Hz ≤ f ≤ 66 Hz : ±0.22% ±0.05%	
Accuracy	Sensor only (amplitude) ±(% of reading +% of full scale) full scale is rated current of sensor	DC :±0.2% ±0.02% DC < f ≤ 100 Hz :±0.2% ±0.01% 100 Hz < f ≤ 500 Hz :±0.3% ±0.02% 500 Hz < f ≤ 1 kHz :±0.5% ±0.02% 1 kHz < f ≤ 5 kHz :±1.0% ±0.02% 5 kHz < f ≤ 10 kHz :±1.5% ±0.02% 10 kHz < f ≤ 50 kHz :±1.5% ±0.02% 50 kHz < f ≤ 100 kHz :±1.50% ±0.02% 50 kHz < f ≤ 500 kHz :±1.50% ±0.05% 100 kHz < f ≤ 300 kHz :±15% ±0.05% 300 kHz < f ≤ 500 kHz :±15% ±0.05%	DC : ±0.2% ±0.05% DC < f ≤ 100 Hz : ±0.2% ±0.01% 100 Hz < f ≤ 500 Hz : ±0.3% ±0.02% 500 Hz < f ≤ 1 kHz : ±0.5% ±0.02% 1 kHz < f ≤ 5 kHz : ±1.0% ±0.02% 5 kHz < f ≤ 10 kHz : ±1.5% ±0.02% 10 kHz < f ≤ 50 kHz : ±2.0% ±0.02% 50 kHz < f ≤ 100 kHz : ±5.0% ±0.05% 500 kHz < f ≤ 300 kHz : ±0.0% ±0.05% 300 kHz < f ≤ 500 kHz : ±10.05% 500 kHz < f ≤ 500 kHz : ±10.05%	
_	perating Temperature	-40°C to 85°C (-40°F to 185°F)	-40°C to 85°C (-40°F to 185°F)	
_	aximum rated voltage to earth	CATIII 1000 V 153 (6.02") W × 67 (2.64") H × 25 (0.98") D mm Cable length: 3 m (9.84 ft)	CATIII 1000 V 153 (6.02") W × 67 (2.64") H × 25 (0.98") D mm Cable length: 3 m (9.84 ft)	
Ma	ass	Approx. 370 g (13.1 oz)	Approx. 350 g (12.3 oz)	
Derating properties		000 A	E 45 40 A	

 $^{^{\}star 2}\,\pm (\%$ of reading + % of range) , range is PW6001

CT6841A: Add ±1% of the range for the 4A range, ±0.5% of the range for the 8A range, and ±0.1% of the range for the 2A range.

CT6841A: Add ±2% of the range for the 400 mA range, ±1% of the range for the 800 mA range, and ±0.1% of the range for the 2A range.

Custom cable lengths also available. Please inquire with your Hioki distributor.

Wide-band probes (connect to Probe2 input terminal)

	3273-50	3274	3275	3276
Appearance	500			00
Rated current	30 A AC/DC	150 A AC/DC	500 A AC/DC	30 A AC/DC
Frequency band	DC to 50 MHz (-3 dB)	DC to 10 MHz (-3 dB)	DC to 2 MHz (-3 dB)	DC to 100 MHz (-3 dB)
Diameter of measurable conductors	Max.φ 5 mm (0.20") (insulated conductors)	Max.φ 20 mm (0.79") (insulated conductors)	Max.φ 20 mm (0.79") (insulated conductors)	Max.φ 5 mm (0.20") (insulated conductors)
Basic accuracy	0 to 30 A rms ±1.0% rdg. ±1 mV 30 A rms to 50 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 150 A rms ±1.0% rdg. ±1 mV 150 A rms to 300 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 500 A rms ±1.0% rdg. ±5 mV 500 A rms to 700 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)	0 to 30 A rms ±1.0% rdg. ±1 mV 30 A rms to 50 A peak ±2.0% rdg. (At DC and 45 to 66 Hz)
Operating temperature	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)
Effect of external magnetic fields	20 mA equivalent or lower (400 A/m, 60 Hz and DC)	150 mA equivalent or lower (400 A/m, 60 Hz and DC)	400 mA equivalent or lower (400 A/m, 60 Hz and DC)	400 mA equivalent or lower (400 A/m, 60 Hz and DC)
Dimensions	175W (6.89") × 18H(0.71") × 40D (1.57") mm Cable length: 1.5 m	176W (6.93") × 69H (2.72") × 27D(1.06") mm Cable length: 2 m	176W (6.93") × 69H (2.72") × 27D(1.06") mm Cable length: 2 m	175W (6.89") × 18H(0.71") × 40D (1.57") mm Cable length: 1.5 m
Mass	230 g (8.1 oz)	500 g (17.6 oz)	520 g (18.3 oz)	240 g (8.5 oz)
Derating properties	9 30 20 20 20 20 20 20 20 20 20 20 20 20 20	September 150	Wednesd (American Program of State Control of State Contr	Se

	CT6700	CT6701	
Appearance	900	900	
Rated current	5 A AC/DC	5 A AC/DC	
Frequency band	DC to 50 MHz (-3 dB)	DC to 120 MHz (-3 dB)	
Diameter of measurable conductors	Max.ø 5 mm (0.20") (insulated conductors)	Max.ø 5 mm (0.20") (insulated conductors)	
typical ±1.0% rdg. ±1 mV		typical ±1.0% rdg. ±1 mV ±3.0% rdg. ±1 mV (At DC and 45 to 66 Hz)	
Operating temperature	0°C to 40°C (32°F to 104°F)	0°C to 40°C (32°F to 104°F)	
Effects of external magnetic fields	20 mA equivalent or lower (400 A/m, 60 Hz and DC)	5 mA equivalent or lower (400 A/m, 60 Hz and DC)	
Dimensions	155W (6.10") × 18H(0.71") × 26D (1.02") mm Cable length: 1.5 m	155W (6.10") × 18H(0.71") × 26D (1.02") mm Cable length: 1.5 m	
Mass	250 g (8.8 oz)	250 g (8.8 oz)	
Derating properties	6 5 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	Frequency [Hz]	

Sensor switching method



High accuracy sensor terminal: Slide the cover to the left.

When connecting

CT6877A, CT6877A-1, CT6904A, CT6904A-1, CT6904A-2, CT6904-3, CT6876A, CT6876A-1, CT6875A, CT6875A-1, CT6873, CT6873-01, CT6863-05, CT6872, CT6872-01, CT6862-05, CT6841A, CT6843A, CT6844A, CT6845A, CT6846A, PW9100A-3, PW9100A-4



Wideband probe terminal: Slide the cover to the right.

When connecting

3273-50, 3274, 3275, 3276, CT6700 or CT6701

High-accuracy sensors: direct connection type (connect to Probe1 input terminal)

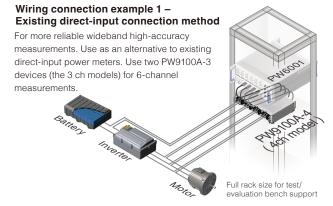
The newly developed DCCT method provides world-leading measurement bands and accuracy at a 50 A rating. Delivering a direct-coupled type current testing tool that brings out the PW6001 POWER ANALYZER's maximum potential.

(A 5 A rated version is also available. Contact us for more information.)

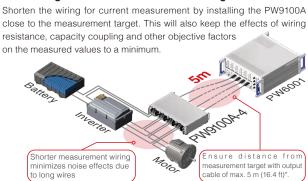
(A 5 A-rated version is also available. Contact us for more information.)				
	AC/DC CURRENT BOX PW9100A-3	AC/DC CURRENT BOX PW9100A-4		
External Appearance				
Number of input channels	3 ch	4 ch		
Rated primary current	50 A A	AC/DC		
Frequency band	DC to 3.5 M	MHz (-3 dB)		
Measurement terminals	Terminal block (with sa	lfety cover), M6 screws		
Basic accuracy	(At 45 ≤ f	(amplitude), ±0.1 ° (phase) ≤ 65 Hz) f.s. (amplitude), (At DC)		
Frequency response (Amplitude)	to 45 Hz: ±0.1% rdg, ±0.02% f.s. to 1 kHz: ±0.1% rdg, ±0.01% f.s. to 50 kHz: ±1% rdg, ±0.02% f.s. to 100 kHz: ±2% rdg, ±0.05% f.s. to 1 MHz: ±10% rdg, ±0.05% f.s. 3.5 MHz: -3 dB Typical			
Input resistance	1.5 mΩ or less	(50 Hz/60 Hz)		
Operating temperature range		40°C (32°F to 104°F), less (no condensation)		
Effects of common-mode voltage (CMRR)		er, 100 kHz: 120 dB or greater /common-mode voltage)		
Maximum voltage to ground		600 V (measurement category III), overvoltage: 6000 V		
Dimensions		3.46 in) H × 260 mm (10.24 in) D, 0.8 m (2.62 ft)		
Mass	3.7 kg (130.5 oz)	4.3 kg (151.7 oz)		
Derating Characteristics Denote the second contraction of the second				
PW6001 Combined ±(%	6 of reading + % of range), range i	s PW6001		
3 3				

Current (I)

 $45 \text{ Hz} \le \text{f} \le 66 \text{ Hz}$



Wiring connection example 2 – Introducing a new and innovative measuring method



*Requires CT9902 EXTENSION CABLE

Active power (P)

±0.04% ±0.035%

Model: POWER ANALYZER PW6001

Model No. Number of (Order Code) built-in channels		Motor Analysis & D/A Output
PW6001-01	1ch	_
PW6001-02	2ch	_
PW6001-03	3ch	_
PW6001-04	4ch	_
PW6001-05	5ch	_
PW6001-06	6ch	_
PW6001-11	1ch	✓
PW6001-12	2ch	✓
PW6001-13	3ch	✓
PW6001-14	4ch	✓
PW6001-15	5ch	✓
PW6001-16	6ch	✓



PW6001-16 (with 6 channels and Motor Analysis & D/A Output

Accessories: Instruction manual \times 1, power cord \times 1, D-sub 25-pin connector (PW6001-11 to -16 only) \times 1

- The separately sold voltage cord and current sensor are required for taking measurements.
- Specify the number of built-in channels and whether to include the Motor Analysis & D/A Output upon order for factory installation. Please contact your local Hioki sales subsidiary or branch for changes after shipment.

$\textbf{Current measurement options} \ (\textbf{High accuracy: pass-through, clamp, direct connection type})$

Model No. (Order Code)	Model	Rated current	Frequency band	Number of channels Cable length
CT6877A	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	3 m
CT6877A-1	AC/DC CURRENT SENSOR	2000 A rms	DC to 1 MHz	10 m
CT6876A	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.5 MHz	3 m
CT6876A-1	AC/DC CURRENT SENSOR	1000 A rms	DC to 1.2 MHz	10 m
CT6904A-2*	AC/DC CURRENT SENSOR	800 A rms	DC to 4 MHz	3 m
CT6904A-3*	AC/DC CURRENT SENSOR	800 A rms	DC to 2 MHz	10 m
CT6904A	AC/DC CURRENT SENSOR	500 A rms	DC to 4 MHz	3 m
CT6904A-1*	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	10 m
CT6875A	AC/DC CURRENT SENSOR	500 A rms	DC to 2 MHz	3 m
CT6875A-1	AC/DC CURRENT SENSOR	500 A rms	DC to 1.5 MHz	10 m
CT6873	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	3 m
CT6873-01	AC/DC CURRENT SENSOR	200 A rms	DC to 10 MHz	10 m
CT6863-05	AC/DC CURRENT SENSOR	200 A rms	DC to 500 kHz	3 m
CT6872	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	3 m
CT6872-01	AC/DC CURRENT SENSOR	50 A rms	DC to 10 MHz	10 m
CT6862-05	AC/DC CURRENT SENSOR	50 A rms	DC to 1 MHz	3 m
CT6846A	AC/DC CURRENT PROBE	1000 A rms	DC to 100 kHz	3 m
CT6845A	AC/DC CURRENT PROBE	500 A rms	DC to 200 kHz	3 m
CT6844A	AC/DC CURRENT PROBE	500 A rms	DC to 500 kHz	3 m
CT6843A	AAC/DC CURRENT PROBE	200 A rms	DC to 700 kHz	3 m
CT6841A	AC/DC CURRENT PROBE	20 A rms	DC to 2 MHz	3 m
PW9100A-3	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	3 ch
PW9100A-4	AC/DC CURRENT BOX	50 A rms	DC to 3.5 MHz	4 ch

^{*} Build-to-order product

Current measurement options (Wide-band probes)

Our ent measurement options (wide-band probes)						
Model No. (Order Code)	Model	Rated current	Frequency band	Sensor cable length		
3273-50	CLAMP ON PROBE	30 A rms	DC to 50 MHz	1.5 m		
3274	CLAMP ON PROBE	150 A rms	DC to 10 MHz	2 m		
3275	CLAMP ON PROBE	500 A rms	DC to 2 MHz	2 m		
3276	CLAMP ON PROBE	30 A rms	DC to 100 MHz	1.5 m		
CT9700	CURRENT PROBE	5 A rms	DC to 50 MHz	1.5 m		
CT9701	CURRENT PROBE	5 A rms	DC to 120 MHz	1.5 m		

Voltage Measurement Options



VOLTAGE CORD L9438-50

banana-banana (red. black, 1 each), alligator clip. spiral tube, approx. 3 m (9.84 ft.) length CAT IV 600 V, CAT III 1000 V



VOLTAGE CORD L1000

banana-banana (red, yellow, blue, gray, 1 each, black × 4), alligator clip, approx. 3 m (9.84 ft.) length CAT IV 600 V, CAT III 1000 V



CONNECTION CORD L9257

banana-banana (red, black, 1 each), alligator clip, approx. 1.2 m (3.94 ft.) length CAT IV 600 V, CAT III 1000 V



AC/DC HIGH VOLTAGE DIVIDER VT1005

VT1005 divides and outputs voltages of up to 5000 V.



GRABBER CLIP L9243

GRABBER CLIP (red. black, 1 each) Attaches to the tip of the banana plug cable



PATCH CORD L1021-01

for branching voltage input, banana branch to banana clip (red × 1), 0.5 m (1.64 ft.) length CAT IV 600 V, CATIII 1000 V



PATCH CORD L1021-02

for branching voltage input, banana branch to banana clip (black × 1), 0.5 m (1.64 ft.) length CAT IV600 V, CATIII 1000 V



VOLTAGE CORD L1050-01, L1050-03

For VT1005

L1050-01: 1.6 m (5.25 ft), L1050-03: 3.0 m (9.84 ft)

Connection Options



CONNECTION CORD

L9217, L9217-01, L9217-02

For motor analysis input and connection to VT1005, BNC-BNC. L9217: 1.6 m (5.25 ft), L9217-01: 3.0 m (9.84 ft), L9217-02: 10 m (32.81 ft)



OPTICAL CONNECTION CABLE L6000

50 µm, 125 µm multi-mode fiber equivalent, 10 m (32.81 ft.) length



CONNECTION CABLE 9444

For external control, 9pin-9pin, straight cable, 1.5 m (4.92 ft.) lenath



CONVERSION CABLE CT9900

For use with CT6862, CT6863, CT6841, CT6843, CT6844, CT6845, CT6846.



CONNECTION CABLECT9904

Cable length 1 m; required in order to connect the CT9557's added waveform output terminal to the PW6001.

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CONVERSION ADAPTER 9704

For connection to VT1005 BNC-to-banana plug



LAN CABLE 9642

Supplied with straight to cross conversion connector, Cable length: 5 m (16.41 ft)



RS-232C CABLE 9637

9pin-9pin cross Cable length: 1.8 m (5.91 ft)



GP-IB CONNECTOR CABLE 9151-02

2 m (6.56 ft.) length



SENSOR UNIT CT9557

Merges up to four current sensor output waveforms on a single channel, for output to PW6001.

Other -

The following made-to-order items are also available. Please contact your Hioki distributor or subsidiary for more information.

- Carrying case (hard trunk, with casters)
- D/A output cable, D-sub 25-pin-BNC (male), 20 ch conversion, 2.5 m (8.20 ft) length
- Bluetooth® serial converter adapter cable 1 m (3.28 ft)
- Rackmount fittings (EIA, JIS)
- Optical connection cable, Max. 500 m (1640.55 ft) length
- PW9100 5 A rated version, CT6904 800 A rated version



Rackmount fittings



D/A output cable



Carrying case

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